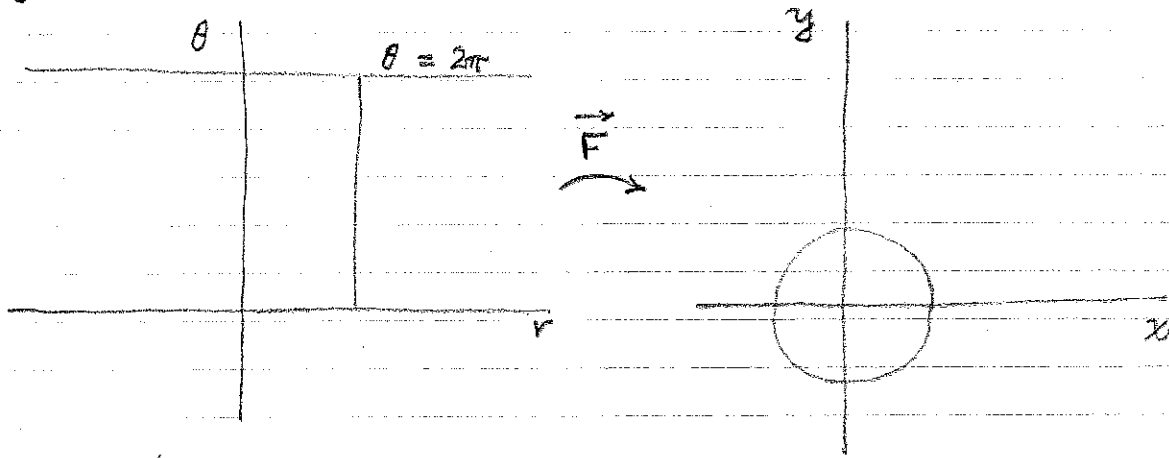


Maths 5B.

Monday, April 11, 2011

APPLICATION OF CHAIN RULE:

$$\begin{pmatrix} x \\ y \end{pmatrix} = \vec{F} \begin{pmatrix} r \\ \theta \end{pmatrix} = \begin{pmatrix} r \cos \theta \\ r \sin \theta \end{pmatrix}$$



$$\vec{G}(t) = \begin{pmatrix} r(t) \\ \theta(t) \end{pmatrix}$$

$$\vec{F} \circ \vec{G}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

CHAIN RULE:

$$\begin{pmatrix} \frac{dx}{dt}(t) \\ \frac{dy}{dt}(t) \end{pmatrix} = D(\vec{F} \circ \vec{G})(t) = D\vec{F}(\vec{G}(t)) \cdot D\vec{G}(t)$$

$$= D\vec{F}(\vec{G}(t)) \begin{pmatrix} \frac{dr}{dt}(t) \\ \frac{d\theta}{dt}(t) \end{pmatrix}$$

$$D\vec{F} = \begin{pmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{pmatrix}$$

$$\begin{pmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{pmatrix} = \begin{pmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{pmatrix} \begin{pmatrix} \frac{dr}{dt} \\ \frac{d\theta}{dt} \end{pmatrix}$$

APPLICATION

$$\begin{cases} \frac{dx}{dt} = -4y \\ \frac{dy}{dt} = 4x \end{cases}$$

CAN WE SIMPLIFY BY CHANGING TO POLAR COORDINATES?

$$\begin{cases} r \cos \theta \frac{dr}{dt} - r \sin \theta \frac{d\theta}{dt} = -4r \sin \theta & \times \cos \theta \\ r \sin \theta \frac{dr}{dt} + r \cos \theta \frac{d\theta}{dt} = 4r \cos \theta & \times \sin \theta \end{cases}$$

$$(\cos^2 \theta + \sin^2 \theta) \frac{dr}{dt} = 0$$

$$\frac{dr}{dt} = 0$$

$$\begin{cases} -r \sin \theta \frac{d\theta}{dt} = -4r \sin \theta & \frac{d\theta}{dt} = 4 \\ r \cos \theta \frac{d\theta}{dt} = 4r \cos \theta \end{cases}$$

$$\begin{cases} \frac{dr}{dt} = 0 \\ \frac{d\theta}{dt} = 4 \end{cases} \quad \begin{cases} r = a \\ \theta = 4t + b \end{cases}$$

$$\begin{cases} x = a \cos(4t + b) \\ y = a \sin(4t + b) \end{cases}$$

$$\begin{cases} m \frac{d^2x}{dt^2} = -\frac{GMm}{r^2} \frac{x}{r} \\ m \frac{d^2y}{dt^2} = -\frac{GMm}{r^2} \frac{y}{r} \end{cases} \quad \leftarrow \text{NEWTON'S EQN FOR PLANETARY MOTION}$$

(mass)(acceleration) = gravitational force

Easier to solve in polar coordinates.

$\gamma : [a, b] \rightarrow \mathbb{R}^3$ represents a parametrized curve

$$\gamma(t) = \begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = \text{position of a moving particle in } \mathbb{R}^3$$

image of γ is an unparametrized curve in \mathbb{R}^3

$$\gamma'(t) = \begin{pmatrix} \frac{dx}{dt}(t) \\ \frac{dy}{dt}(t) \\ \frac{dz}{dt}(t) \end{pmatrix} = \text{velocity of particle at time } t.$$

$$|\gamma'(t)| = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

$$\int_a^b |\gamma'(t)| dt = \int_a^b (\text{speed}) d(\text{time}) = \text{distance travelled}$$

If $\gamma : [a, b] \rightarrow \mathbb{R}^3$ is a parametrization of a curve C ,

$$L(\gamma) = \text{length of } C = \int_a^b |\gamma'(t)| dt$$

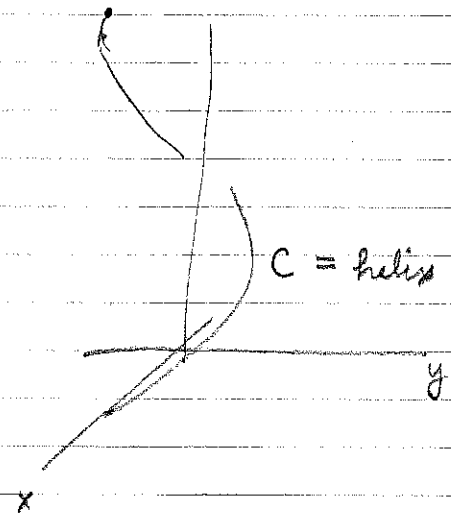
EXAMPLE:

$$\gamma : [0, 2\pi] \rightarrow \mathbb{R}^3 \quad \gamma(t) = \begin{pmatrix} \cos t \\ \sin t \\ t \end{pmatrix}$$

$$\gamma'(t) = \begin{pmatrix} -\sin t \\ \cos t \\ 1 \end{pmatrix}$$

$$|\gamma'(t)| = \sqrt{\sin^2 t + \cos^2 t + 1}$$

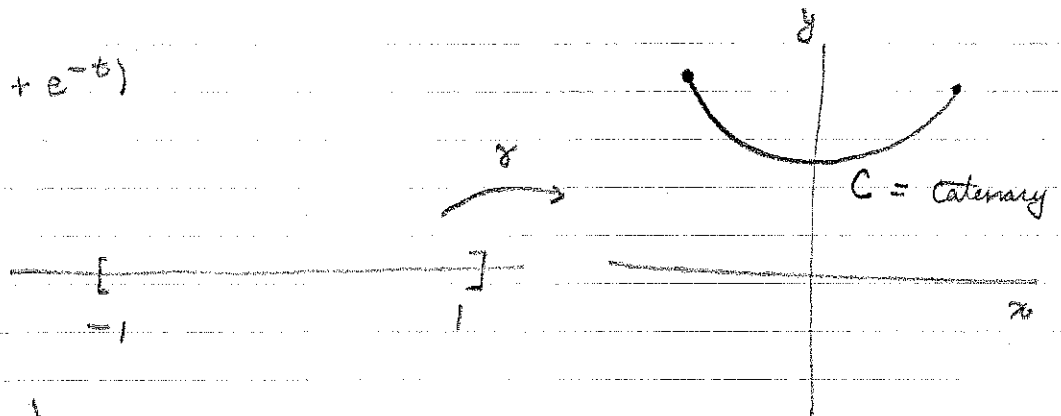
$$= \sqrt{2}$$



$$L(\gamma) = \int_0^{2\pi} |\gamma'(t)| dt = \int_0^{2\pi} \sqrt{2} dt = \boxed{2\pi\sqrt{2}}$$

$$\gamma: [-1, 1] \rightarrow \mathbb{R}^2, \quad \gamma(t) = \begin{pmatrix} t \\ \cosh t \end{pmatrix}$$

$$\cosh t = \frac{1}{2}(e^t + e^{-t})$$



$$\gamma'(t) = \begin{pmatrix} 1 \\ \sinh t \end{pmatrix}$$

$$|\gamma'(t)| = \sqrt{1 + \sinh^2 t} = \sqrt{\cosh^2 t} \\ = \cosh t$$

$$L(\gamma) = \int_{-1}^1 |\gamma'(t)| dt = \int_{-1}^1 \cosh t dt = \sinh t \Big|_{-1}^1 = \sinh(1) - \sinh(-1) \\ = 2 \sinh(1) = e^1 - e^{-1} = \boxed{e - \frac{1}{e}}$$