

Math. 5B.

Monday, May 2, 2011

Gravitation according to Newton:

Force = (mass)(acceleration)

$$\text{Gravitational Force} = -\frac{GMm}{x^2+y^2} \left(\frac{x}{\sqrt{x^2+y^2}} \vec{i} + \frac{y}{\sqrt{x^2+y^2}} \vec{j} \right)$$

$$m \begin{pmatrix} \frac{dx}{dt^2} \\ \frac{dy}{dt^2} \end{pmatrix} = -\frac{GMm}{x^2+y^2} \begin{pmatrix} \frac{x}{\sqrt{x^2+y^2}} \\ \frac{y}{\sqrt{x^2+y^2}} \end{pmatrix}$$

$$(*) \quad m \frac{d^2 \vec{r}}{dt^2} = -\frac{GMm}{|\vec{r}|^2} \left(\frac{-\vec{r}}{|\vec{r}|} \right) = -\nabla V$$

How to simplify these equations?

$$\text{Let } V = -\frac{GMm}{|\vec{r}|} = -\frac{GMm}{\sqrt{x^2+y^2}}$$

$$\text{Then } \nabla V = +GMm \frac{1}{2} (x^2+y^2)^{-3/2} \begin{pmatrix} 2x \\ 2y \end{pmatrix} \quad -\nabla V = -\frac{GMm}{x^2+y^2} \begin{pmatrix} \frac{x}{\sqrt{x^2+y^2}} \\ \frac{y}{\sqrt{x^2+y^2}} \end{pmatrix}$$

 $V(x,y)$ = potential energy at (x,y) Claims: Along a solⁿ, \dot{r} is

$$\frac{1}{2} m \left| \frac{d\vec{r}}{dt} \right|^2 + V(x,y) = \text{constant}$$

$$\text{Proof: } \frac{d}{dt} \left[\frac{1}{2} m \left| \frac{d\vec{r}}{dt} \right|^2 + V(x,y) \right]$$

$$= m \frac{d\vec{r}}{dt} \cdot \frac{d^2 \vec{r}}{dt^2} + \frac{dV}{dt} = m \frac{d\vec{r}}{dt} \cdot \frac{d^2 \vec{r}}{dt^2} + \nabla V \cdot \frac{d\vec{r}}{dt} = \left(m \frac{d^2 \vec{r}}{dt^2} + \nabla V \right) \cdot \frac{d\vec{r}}{dt} = 0$$

$$\left\{ \frac{1}{2} m \left[\left(\frac{dx}{dt} \right)^2 + \left(\frac{dy}{dt} \right)^2 \right] + V(x,y) \right\} = E = \text{energy}$$

$$\left\{ m x \frac{dy}{dt} - m y \frac{dx}{dt} \right\} = L = \text{angular momentum (by a similar calculation)}$$

Now transform to polar coordinates using chain rule.

Using techniques of ODE's Newton could then derive Kepler's

3 laws of planetary motion.

Definition A vector field $\vec{F}(x_1, \dots, x_n)$ is said to be conservative

if $\vec{F}(x_1, \dots, x_n) = \nabla f(x_1, \dots, x_n)$ for some function $f: \mathbb{R}^n \rightarrow \mathbb{R}$.

Theorem. Suppose $\vec{z}: [0, 1] \rightarrow \mathbb{R}^n$ is the parametrization of a directed curve \vec{C} from (a_1, \dots, a_n) to (b_1, \dots, b_n) .

$$\text{Then } \int_{\vec{C}} \nabla f \cdot \vec{T} ds = \int_0^1 \nabla f \cdot d\vec{z} = f(b_1, \dots, b_n) - f(a_1, \dots, a_n)$$

$$\text{Proof: } d\vec{z} = \begin{pmatrix} dx_1 \\ \vdots \\ dx_n \end{pmatrix} \quad \nabla f = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix} \quad z = f(x_1, \dots, x_n) \\ z(t) = f(x_1(t), \dots, x_n(t))$$

$$\int_{\vec{C}} \nabla f \cdot d\vec{z} = \int_0^1 \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix} \cdot \begin{pmatrix} dx_1 \\ \vdots \\ dx_n \end{pmatrix} = \int_0^1 \frac{\partial f}{\partial x_1} dx_1 + \dots + \frac{\partial f}{\partial x_n} dx_n$$

$$= \int_0^1 \left(\frac{\partial f}{\partial x_1} \frac{dx_1}{dt} + \dots + \frac{\partial f}{\partial x_n} \frac{dx_n}{dt} \right) dt = \int_0^1 \frac{d}{dt} (z(t)) dt = z(1) - z(0)$$

$$= f(b_1, \dots, b_n) - f(a_1, \dots, a_n).$$

APPLICATION. Let \vec{C} be the line segment from

$(1, 3, 4)$ to $(3, 4, 1)$. What is

$$\int_{\vec{C}} \nabla f \cdot \vec{T} ds \quad \text{when} \quad f(x, y, z) = e^{-x^2 + y^2 + z^2} + x$$

$$\begin{aligned} \text{SOLUTION: } \int_C \nabla f \cdot d\vec{x} &= f(3, 4, 1) - f(1, 3, 4) \\ &= e^{-3^2-4^2-1} + 3 - e^{-1-3^2-4^2} - 1 = \boxed{2} \end{aligned}$$

$$\text{Suppose } \vec{F}(x, y) = \begin{pmatrix} M(x, y) \\ N(x, y) \end{pmatrix}$$

$$\text{When is } \vec{F} \text{ conservative? When is } \vec{F} = \begin{pmatrix} M \\ N \end{pmatrix} = \nabla f = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{pmatrix}$$

$$\begin{cases} M = \frac{\partial f}{\partial x} \\ N = \frac{\partial f}{\partial y} \end{cases}$$

$$\frac{\partial N}{\partial x} = \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial M}{\partial y}$$

Theorem. $\forall M(x, y)$ and $N(x, y)$ are well-behaved functions in \mathbb{R}^2 , then

$$\vec{F} = \begin{pmatrix} M \\ N \end{pmatrix} = \nabla f \text{ for some } f \Leftrightarrow \boxed{\frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}}$$

$$\text{Example: } \vec{F}(x, y) = \begin{pmatrix} M(x, y) \\ N(x, y) \end{pmatrix} = \begin{pmatrix} -y \\ x \end{pmatrix}$$

$$\text{Is } \vec{F} \text{ conservative? } \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} = 1 - (-1) = 2 \neq 0, \text{ NO.}$$

USEFUL NOTATION. $\forall f(x, y)$ is a smooth function

$$df = \nabla f \cdot d\vec{x} = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy.$$

$$\text{CONSIDER THE DE } \frac{dy}{dx} = -\frac{y}{x}$$

$$x dy = -y dx \quad y dx + x dy = 0$$

$$\vec{F} \cdot d\vec{x} = 0, \text{ where } \vec{F} = \begin{pmatrix} y \\ x \end{pmatrix}$$

In this case, $\frac{\partial N}{\partial x} = 1 = \frac{\partial M}{\partial y}$, so \vec{F} is conservative

$$\vec{F} = \nabla f \text{ where } f(x, y) = xy$$

$$d(xy) = \frac{\partial(xy)}{\partial x} dx + \frac{\partial(xy)}{\partial y} dy = y dx + x dy$$

DE can be rewritten as $df = 0$, where $f = xy$

GENERAL SOLUTION TO $\frac{dy}{dx} = -\frac{y}{x}$ is $\boxed{xy = C}$

$$\vec{F}(x, y) = \begin{pmatrix} \sin y + \cos x \\ (x+1) \cos y \end{pmatrix} = \begin{pmatrix} M(x, y) \\ N(x, y) \end{pmatrix}$$

Is \vec{F} conservative? $\frac{\partial N}{\partial x} = \cos y$, $\frac{\partial M}{\partial y} = \cos y$. YES

$$\frac{\partial f}{\partial x} = \sin y + \cos x \Rightarrow f = x \sin y + \sin x + g(y)$$

$$\frac{\partial f}{\partial y} = (x+1) \cos y \Rightarrow f = (x+1) \sin y + h(x)$$

$$\boxed{f(x, y) = x \sin y + \sin x + \sin y}$$