

1. TANGENT AND COTANGENT SPACE

Definition 1.1. A **topological manifold** M is a topological space, which is Hausdorff, has a countable basis for the topology, and which is locally homeomorphic to \mathbb{R}^n . (That is $\forall p \in M, \exists U$, an open neighbourhood of p , and a homeomorphism $h: U \rightarrow U' \subset \mathbb{R}^n$.)

Example 1.2.

Definition 1.3. A chart for M is any such homeomorphism $h: U \rightarrow U'$. An atlas is a collection of charts

$$\{h_\alpha \mid \alpha \in A\},$$

such that $\cup U_\alpha = M$.

Given two charts U_α and U_β , we have a diagram

$$\begin{array}{ccc} & U_\alpha \cap U_\beta & \\ h_\alpha \swarrow & & \searrow h_\beta \\ U'_\alpha & \xrightarrow{h_{\alpha\beta} = h_\beta \circ h_{\alpha^{-1}}} & U'_\beta \end{array}$$

Definition 1.4. A **differentiable** (or C^∞) structure on M is an atlas such that $h_{\alpha\beta}$ is differentiable.

There are three different ways to define and think of the tangent space:

- (A) the algebraist's
- (Ph) the physicists's
- (G) the geometer's.

1.1. **Algebraist's way.** First the algebraic way:

Definition 1.5. We say that two functions f and $g: M \rightarrow N$ are equivalent, at $p \in M$, if there exists a neighbourhood V of p such that $f|_V = g|_V$. The equivalence classes are called **germs**.

Equivalently, a germ is a pair (f, U) , where f is an function on U an open neighbourhood of p and two such germs (f, U) and (g, V) are considered equivalent, if there is an open subset $W \subset U \cap V$ such that $f|_W = g|_W$.

We denote the set of all C^∞ -germs $f: (M, p) \rightarrow \mathbb{R}$ by $\mathcal{C}_{M,p}^\infty$. $\mathcal{C}_{M,p}^\infty$ is a real algebra: one can certainly add and multiply germs, just like one

adds and multiplies functions. Given a germ $\bar{f}: (M, p) \rightarrow (N, q)$, we get an algebra homomorphism

$$f^*: \mathcal{C}_{N,q}^\infty \rightarrow \mathcal{C}_{M,p}^\infty \quad \text{given by} \quad \bar{\phi} \rightarrow \bar{\phi} \circ \bar{f}$$

Note that f^* is functorial: the star of the identity is the identity and $(g \circ f)^* = f^* \circ g^*$. Note that if h is a chart which sends p to 0, then

$$h^*: \mathcal{C}_{M,p}^\infty \rightarrow \mathcal{C}_{\mathbb{R},0}^\infty,$$

is an isomorphism.

Definition 1.6 (Algebraists). *Let M be a C^∞ -manifold and let $p \in M$. A **derivation** of $\mathcal{C}_{M,p}^\infty$ is a linear map $X: \mathcal{C}_{M,p}^\infty \rightarrow \mathbb{R}$ such that*

$$X(\bar{\phi} \circ \bar{\psi}) = X(\bar{\phi}) \cdot \bar{\psi}(p) + \bar{\phi}(p) \cdot X(\bar{\psi}).$$

Then the tangent space to M at p , $T_p M$, is the set of all derivations of $\mathcal{C}_{M,p}^\infty$.

Now if we are given a germ

$$\bar{f}: (M, p) \rightarrow (N, q)$$

then we get a map

$$T_p f: T_p M \rightarrow T_q N$$

as follows. Given a derivation $X: \mathcal{C}_{M,p}^\infty \rightarrow \mathbb{R}$, let $T_p(X) = X \circ f^*$, where f^* is defined as above.

Note also that the set of derivations is indeed a vector space. Also

$$\begin{aligned} X(1) &= X(1 \cdot 1) \\ &= 1 \cdot X(1) + X(1) \cdot 1 \\ &= X(1) + X(1). \end{aligned}$$

So $X(1) = 0$. It follows that $X(c) = 0$, for c any constant. Note that in this way we get a functor, since

$$T_p(\bar{g} \circ \bar{f}) = T_q(\bar{g}) \circ T_p(\bar{f}),$$

where $q = f(p)$. In particular, given a chart $h: M \rightarrow \mathbb{R}^n$, which sends p to 0, we get an isomorphism

$$T_p h: T_p M \rightarrow T_0 \mathbb{R}^n \simeq \mathbb{R}^n.$$

Definition 1.7. *Given coordinates (x_1, x_2, \dots, x_n) on \mathbb{R}^n , the function*

$$\frac{\partial}{\partial x_i}: \mathcal{C}_{\mathbb{R}^n,0}^\infty \rightarrow \mathbb{R} \quad \text{which sends} \quad \bar{\phi} \rightarrow \left. \frac{\partial \bar{\phi}}{\partial x_i} \right|_{x=0}$$

is a derivation.

Lemma 1.8. $\frac{\partial}{\partial x_i}$ are a basis of $T_0\mathbb{R}^n$.

Lemma 1.9. Let U be an open ball about the origin of \mathbb{R}^n , and let

$$f: U \longrightarrow \mathbb{R}^n,$$

be a differentiable function.

Then $\exists f_1, f_2, \dots, f_n$ such that

$$f(x) = f(0) + \sum_{i=1}^n x_i f_i(x).$$

Proof.

$$\begin{aligned} f(x) - f(0) &= \int_0^1 \frac{d}{dt} f(tx_1, tx_2, \dots, tx_n) dt \\ &= \sum_{i=1}^n x_i \int_0^1 \frac{\partial}{\partial x_i} f(tx_1, tx_2, \dots, tx_n) dt, \end{aligned}$$

and so we are done if we set

$$f_i(x) = \int_0^1 \frac{\partial}{\partial x_i} f(tx_1, tx_2, \dots, tx_n) dt.$$

□

Proof of (1.8). Suppose that

$$\sum a_i \frac{\partial}{\partial x_i} = 0.$$

Applying \bar{x}_j to this equation, we get

$$0 = \left(\sum_{i=1}^n \frac{\partial}{\partial x_i} \right) (\bar{x}_j) = a_j.$$

Thus these derivations are certainly linearly independent. Now suppose that $X \in T_0(\mathbb{R}^n)$. Set $a_i = X(\bar{x}_i)$, and

$$Y = X - \sum a_i \frac{\partial}{\partial x_i}.$$

Clearly $Y(\bar{x}_j) = 0$, for every j . Suppose that $\bar{f} \in \mathcal{C}_{\mathbb{R}^n, 0}^\infty$. By (1.9), there are germs \bar{f}_i , such that

$$\bar{f} = \bar{f}(0) + \sum_{i=1}^n \bar{x}_i \bar{f}_i,$$

and so

$$\begin{aligned} Y(\bar{f}) &= Y(\bar{f}(0)) - \sum_{i=1}^n Y(\bar{x}_i) \cdot \bar{f}_i(0) \\ &= 0. \end{aligned}$$

But then $Y = 0$. □

Suppose that we introduce coordinates (x_1, x_2, \dots, x_n) about $p \in M$ and (y_1, y_2, \dots, y_m) about $q \in N$. Then we get a commutative diagram

$$\begin{array}{ccc} (N, p) & \xrightarrow{f} & (M, q) \\ \downarrow & & \downarrow \\ (\mathbb{R}^n, 0) & \xrightarrow{\bar{f}} & (\mathbb{R}^m, 0). \end{array}$$

It is interesting to calculate $T_0\bar{f}$. Pick $\bar{\phi} \in \mathcal{C}_{\mathbb{R}^m, 0}^\infty$. Then

$$\begin{aligned} T_0\bar{f} \left(\frac{\partial}{\partial x_i} \right) (\bar{\phi}) &= \frac{\partial}{\partial x_i} (\bar{\phi} \circ \bar{f}) \\ &= \sum_{j=1}^m \frac{\partial \bar{\phi}}{\partial y_j} (0) \cdot \frac{\partial \bar{f}_j}{\partial x_i} (0). \end{aligned}$$

So

$$T_0\bar{f} \left(\frac{\partial}{\partial x_i} \right) = \sum_{j=1}^m \frac{\partial \bar{f}_j}{\partial x_i} (0) \cdot \frac{\partial}{\partial y_j} (0).$$

The matrix

$$Df = \left(\frac{\partial f_j}{\partial x_i} \right),$$

is the Jacobian of f . If

$$v = \sum a_i \frac{\partial}{\partial x_i} \quad \text{then} \quad T_0fv = \sum_j b_j \frac{\partial}{\partial y_j},$$

where

$$b = (Df(0)) \cdot a.$$

Putting all this together:

Theorem 1.10. *If one introduces coordinates (x_1, x_2, \dots, x_n) and (y_1, y_2, \dots, y_m) around $p \in M^n$ and $q \in N^n$, then the derivations $\frac{\partial}{\partial x_i}$ and $\frac{\partial}{\partial y_j}$ form a basis for T_pM and T_qN , and if $\bar{f}: (M, p) \rightarrow (N, q)$ is a germ, the tangential map $T_p\bar{f}$ is given with respect to these bases as Df_0 .*

So much for the algebraists definition, which although clean, does not always generalise so well (for example to C^p -manifolds or to infinite dimensional manifolds).

1.2. Physicist's Way. Physicists often start with a coordinate version of (1.10). Thus a typical statement might be "A contravariant vector, or a tensor of the first order, is a real n -tuple which transforms according to the Jacobi matrix."

Put differently, first pick one chart $\bar{h}: (M, p) \rightarrow (\mathbb{R}^n, 0)$ and then think of all other charts $\bar{k}: (M, p) \rightarrow (\mathbb{R}^n, 0)$ as being derived from

$$\bar{g} = \bar{k} \circ \bar{h}^{-1}: (\mathbb{R}^n, 0) \rightarrow (\mathbb{R}^n, 0),$$

so that $\bar{k} = \bar{g} \circ \bar{h}$. Denote the set of all such chart germs \bar{g} by \mathcal{G} , which is a group under composition.

Given $\bar{g} \in \mathcal{G}$, assign the Jacobi matrix $Dg(0)$,

$$\mathcal{G} \rightarrow \text{GL}(n, \mathbb{R}).$$

Definition 1.11 (Physicists). *A tangent vector at $p \in M^n$ is a rule which assigns to a chart*

$$\bar{h}: (M, p) \rightarrow (\mathbb{R}^n, 0)$$

a vector (v_1, v_2, \dots, v_n) , so that the vector $Dg(0) \cdot v$ corresponds to the chart germ $\bar{g} \circ \bar{h}$.

Let K_p be the set of all chart germs

$$\bar{h}: (N, p) \rightarrow (\mathbb{R}^n, 0)$$

Then $T_p(M)_{Ph}$ is the set of maps $v: K_p \rightarrow \mathbb{R}^n$ such that

$$v(\bar{g} \circ \bar{h}) = Dg(0)v(\bar{h}) \quad \forall \bar{g} \in \mathcal{G}.$$

To get an element of K_p , all one needs to do is pick a chart \bar{h} and assign a single vector $v \in \mathbb{R}^n$. Thus $T_p(M)_{Ph} \simeq \mathbb{R}^n$.

1.3. Geometer's Way. Now we turn to the geometers. A tangent vector ought to be the velocity vector of a path based at p .

Definition 1.12. *Let W_p be the set of all germs $\bar{w}: (\mathbb{R}, 0) \rightarrow (M, p)$. Let \sim be the equivalence relation $\bar{w} \sim \bar{v}$ iff for every function germ $\bar{f} \in C_{M,p}^\infty$,*

$$\left. \frac{d}{dt} \bar{f} \circ \bar{w} \right|_0 = \left. \frac{d}{dt} \bar{f} \circ \bar{v} \right|_0.$$

The tangent space $T_p M_G$ is then the set of equivalence classes W_p / \sim .

Thus two path germs define the same tangent vector iff they define the same differentiation of functions in the direction of the curve. Given $[w]$, associate a derivation X_w as follows.

$$X_w(\bar{f}) = \left. \frac{d}{dt} \bar{f} \circ \bar{w} \right|_0.$$

We get an injection

$$T_p(M)_G \longrightarrow T_p M \quad \text{which sends} \quad [w] \longrightarrow X_w.$$

The map is also surjective, since if $w(t) = (ta_1, ta_2, \dots, ta_n)$ in local coordinates, then

$$X_w = \sum_{i=1}^n a_i \frac{\partial}{\partial x_i}.$$

With this definition, the tangent map is also very clear. A germ

$$\bar{f}: (M, p) \longrightarrow (N, q)$$

induces

$$T_p M \longrightarrow T_q N \quad \text{where} \quad [w] \longrightarrow [f \circ w].$$

1.4. Cotangent Space.

Definition 1.13. The *space of differential forms at p* is the dual vector space of $T_p M = T_p^* M$.

The dual basis to

$$\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \dots, \frac{\partial}{\partial x_n} \quad \text{is} \quad dx_1, dx_2, \dots, dx_n.$$

The total derivative df of a function

$$f: (M, p) \longrightarrow (N, q)$$

is the dual of the tangential map $T_p f$.

Lemma 1.14. Given $f: \mathbb{R}^n \longrightarrow \mathbb{R}$,

$$df = \left(\frac{\partial f}{\partial x_1} \right) \Big|_0 dx_1 + \left(\frac{\partial f}{\partial x_2} \right) \Big|_0 dx_2 + \dots + \left(\frac{\partial f}{\partial x_n} \right) \Big|_0 dx_n.$$

Proof. First note that

$$df: T_0^* \mathbb{R} \longrightarrow T_0^* \mathbb{R}^n,$$

so that we may identify df with the image of dt . Suppose that we write

$$df = \sum_6 a_i dx_i.$$

Hit both sides with $\frac{\partial}{\partial x_j}$, to get

$$a_j = (df)\left(\frac{\partial}{\partial x_j}\right) = \frac{\partial f}{\partial x_j}.$$

□

In general df is given by the transpose of Df .