

Gradient Flow in the Wasserstein Metric

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NIPS, Optimal Transport & Machine Learning

December 9th, 2017

gradient flow in finite dimensions

A curve $x(t): [0, T] \rightarrow \mathbb{R}^d$ is the **gradient flow** of an energy $E: \mathbb{R}^d \rightarrow \mathbb{R}$ if

$$\frac{d}{dt}x(t) = -\nabla E(x(t))$$

- “ $x(t)$ evolves in the direction of steepest descent of E ”
- **initial value problem**: given $x(0)$, find the gradient flow $x(t)$

Example:

metric	energy functional	gradient flow
(\mathbb{R}^d, \cdot)	$E(x) = \frac{1}{2}x^2$	$\frac{d}{dt}x(t) = -x(t)$

Given $x(0) \in \mathbb{R}^d$, $x(t) = x(0)e^{-t}$ is unique solution of the gradient flow.

gradient flow in finite dimensions

Gradient flows often arise when solving optimization problems:

$$\min_{x \in \mathbb{R}^d} E(x)$$

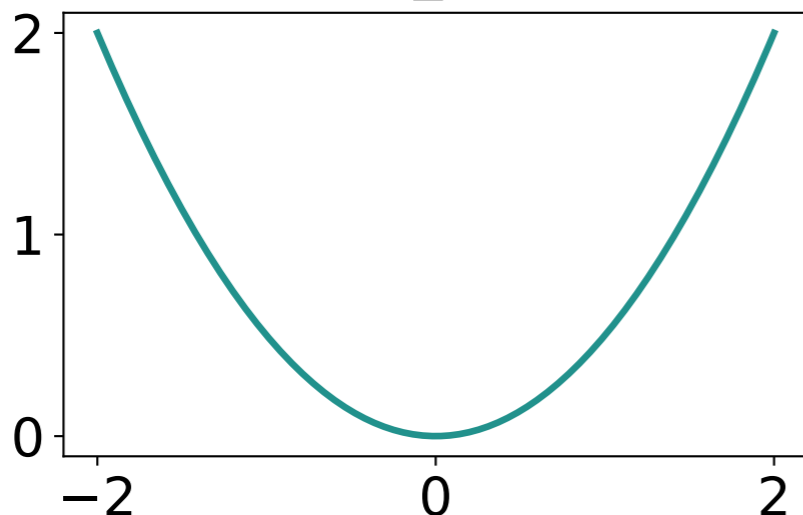
Convexity of the energy determines *stability* and *long time behavior*.

Def: An energy E is λ -convex if $D^2 E \geq \lambda I_{d \times d}$ or, equivalently, if

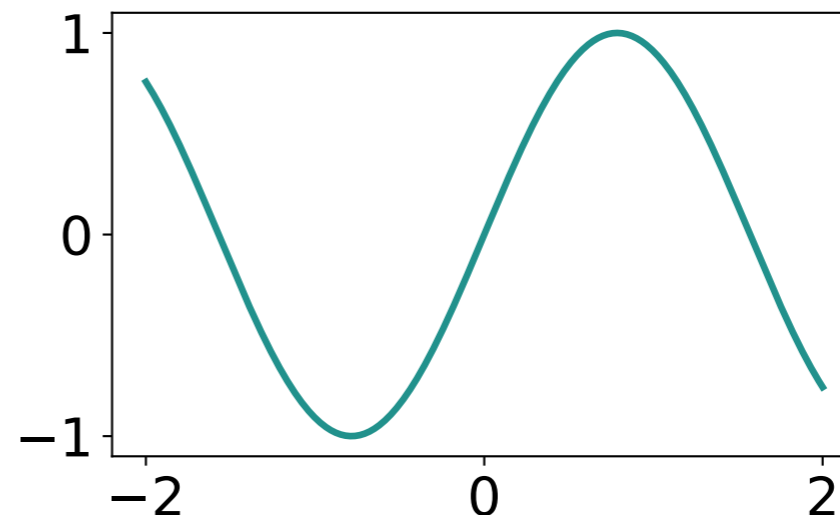
$$E((1-t)x + ty) \leq (1-t)E(x) + tE(y) - t(1-t)\frac{\lambda}{2}|x-y|^2$$

for all $x, y \in \mathbb{R}$, $t \in [0, 1]$.

$$f(x) = \frac{x^2}{2}, \quad \lambda = 1$$



$$f(x) = \sin(x), \quad \lambda = -1$$



gradient flow in finite dimensions

If $E(x)$ is λ -convex, then...

1) **Stability**: for any gradient flows $x(t)$ and $y(t)$,

$$|x(t) - y(t)| \leq e^{-\lambda t} |x(0) - y(0)|$$

2) **long time behavior**: if $\lambda > 0$, there is a unique solution \bar{x} of $\min_{x \in \mathbb{R}^d} E(x)$ and any gradient flow $x(t)$ converges to \bar{x} as $t \rightarrow +\infty$:

$$|x(t) - \bar{x}| \leq e^{-\lambda t} |x(0) - \bar{x}|$$

gradient flow

Gradient flow

prof. Mark. A. Peletier, PhD

Centre for Analysis, Scientific Computing, and Applications
Department of Mathematics and Computer Science

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Where innovation starts

gradient flow

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Where innovation starts

gradient flow with different metrics

In general, given a complete metric space (X, d) , a curve $x(t): \mathbb{R} \rightarrow X$ is the **gradient flow** of an energy $E: X \rightarrow \mathbb{R}$ if

$$\frac{d}{dt}x(t) = -\nabla_X E(x(t))$$

Examples:

Euclidean

L^2

metric (X, d)	(\mathbb{R}^d, \cdot)	$(L^2(\mathbb{R}^d), \ \cdot\ _{L^2})$
def of ∇_X	$\langle \nabla E(x), v \rangle = \lim_{h \rightarrow 0} \frac{E(x + hv) - E(x)}{h}$	$\langle \nabla E(f), g \rangle = \lim_{h \rightarrow 0} \frac{E(f + hg) - E(f)}{h}$
formula for ∇_X	$\nabla_{\mathbb{R}^d} E(x) = \nabla E(x)$	$\nabla_{L^2(\mathbb{R}^d)} E(f) = \frac{\partial E}{\partial f}$
energy	$E(x) = \frac{1}{2}x^2$	$E(f) = \frac{1}{2} \int f ^2$
gradient flow	$\frac{d}{dt}x(t) = -x(t)$	$\frac{d}{dt}f(x, t) = -f(x, t)$

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gradient flow with different metrics

finite difference approximation

$f : \mathbb{R}^d \rightarrow \mathbb{R}$ approximated by $\{f_i\}_{i \in h\mathbb{Z}^d}$

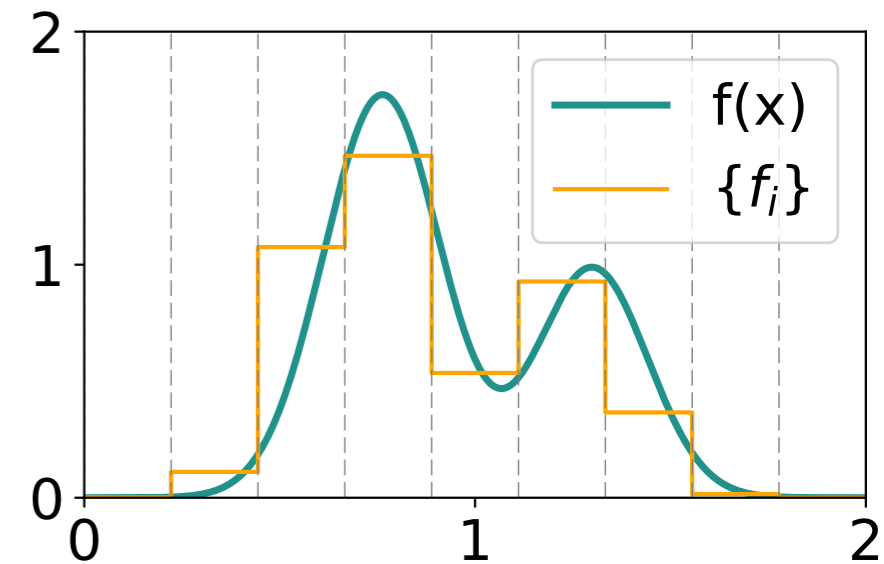
approximate *values* of function

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gradient flow with different metrics

Examples:

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metric (X, d)

$$(\mathbb{R}^d, |\cdot|)$$

$$(\mathcal{P}_2(\mathbb{R}^d), W_2)$$

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formula for ∇_X

$$\nabla_{\mathbb{R}^d} E(x) = \nabla E(x)$$

$$\nabla_{W_2} E(\rho) = -\nabla \cdot \left(\rho \nabla \frac{\partial E}{\partial \rho} \right)$$

energy

$$E(x) = \frac{1}{2} x^2$$

$$E(\rho) = \frac{1}{2} \int x^2 \rho(x) dx$$

gradient flow

$$\frac{d}{dt} x(t) = -x(t)$$

$$\frac{d}{dt} \rho(x, t) = \nabla \cdot (x \rho(x, t))$$

gradient flow with different metrics

$$\langle \nabla E(\mu), -\nabla \cdot (\xi \mu) \rangle_{\text{Tan}_\mu \mathcal{P}_2(\mathbb{R}^d)} = \lim_{h \rightarrow 0} \frac{E((\text{id} + h\xi)\#\mu) - E(\mu)}{h}$$

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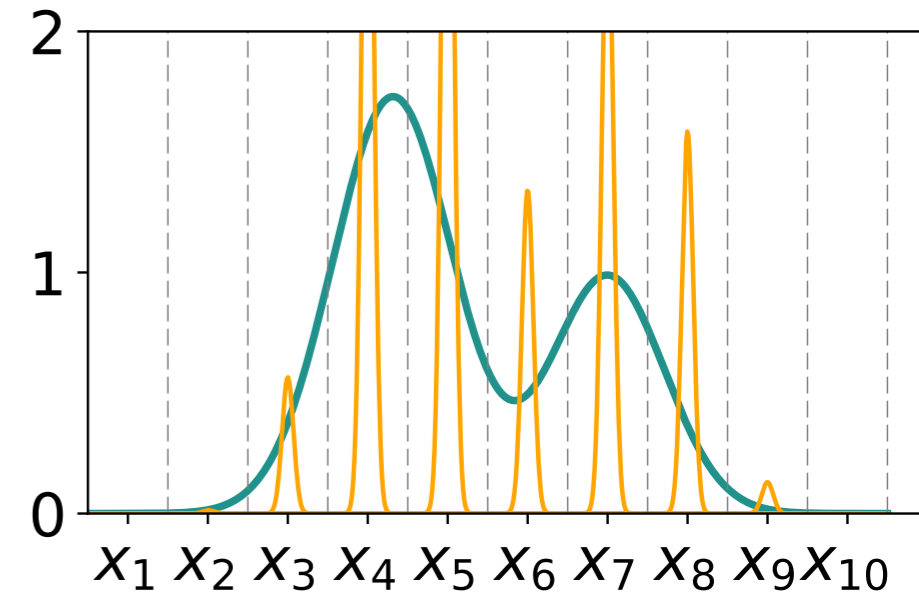
$$\frac{d}{dt} x(t) = -x(t)$$

$$\frac{d}{dt} \rho(x, t) = \Delta \rho(x, t)$$

gradient flow with different metrics

particle approximation

$f : \mathbb{R}^d \rightarrow \mathbb{R}$ approximated by $\sum_{i=1}^N \delta_{x_i} m_i$
 approximate *mass* of function



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interpolating with different metrics

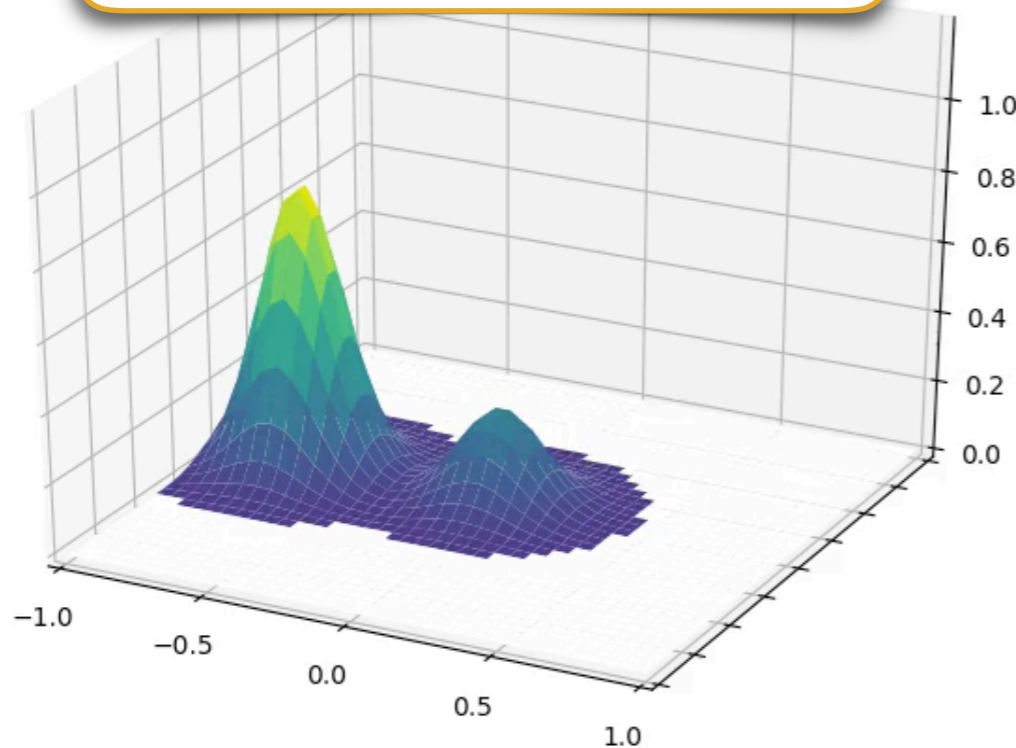
The same dichotomy between **values of a function** and **mass of a function** is also present in the geodesics.

Def: A **constant speed geodesic** between two points ρ_0 and ρ_1 in a metric space (X, d) is any curve $\rho: [0, 1] \rightarrow X$ s.t.

$$\rho(0) = \rho_0, \quad \rho(1) = \rho_1, \quad d(\rho(t), \rho(s)) = |t - s|d(\rho_0, \rho_1)$$

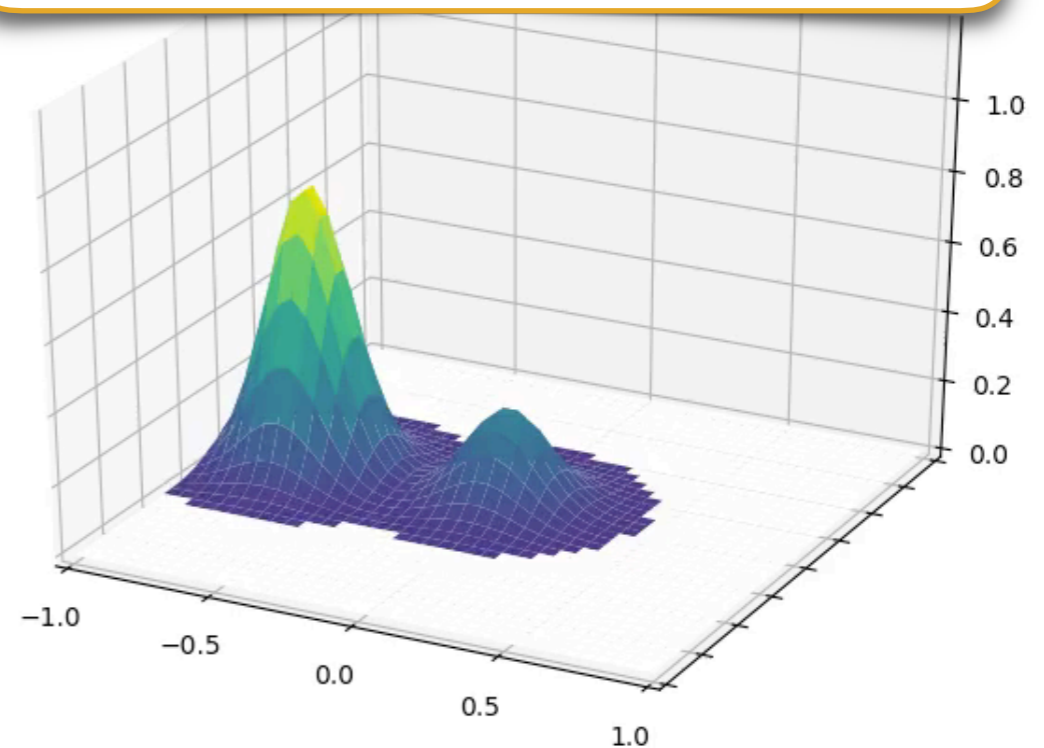
L^2 geodesic

$$\rho(t) = (1 - t)\rho_0 + t\rho_1$$



W_2 geodesic

$$\rho(t) = ((1 - t)\text{id} + tT_{\rho_0}^{\rho_1})\# \rho_0$$



interpolating with different metrics

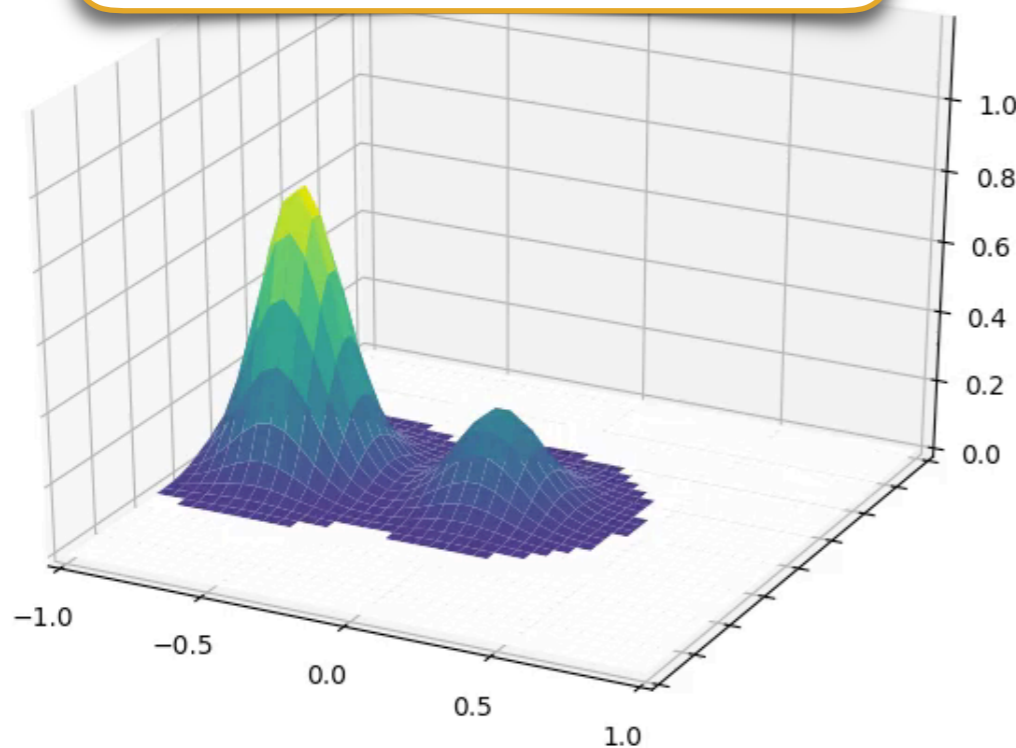
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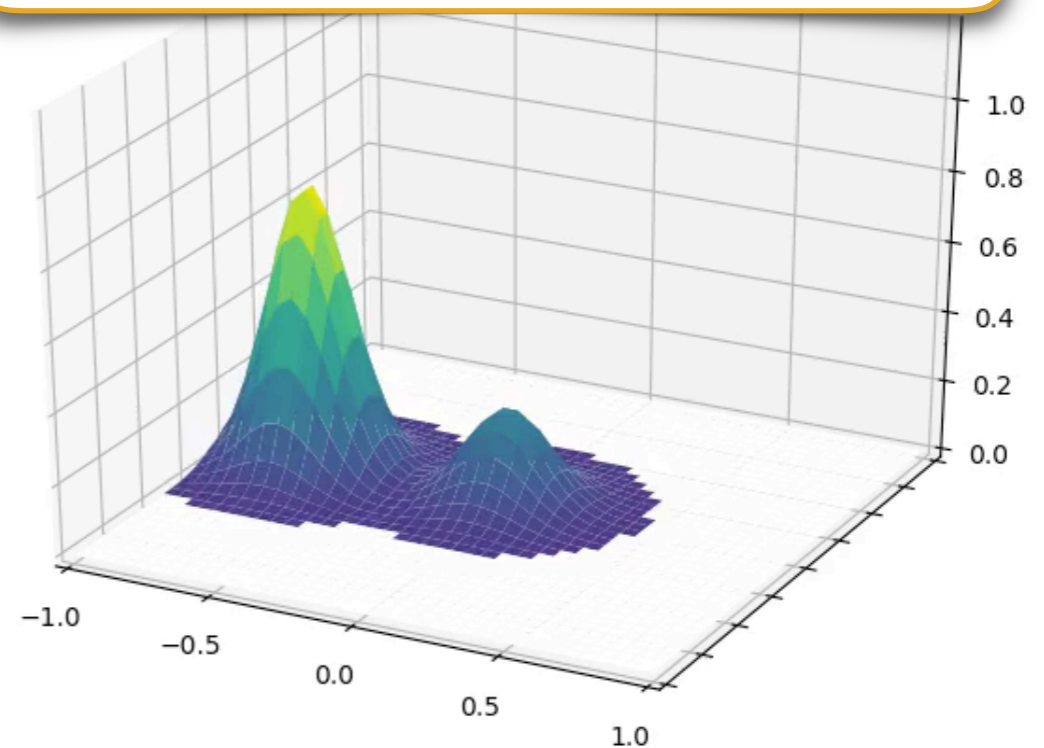
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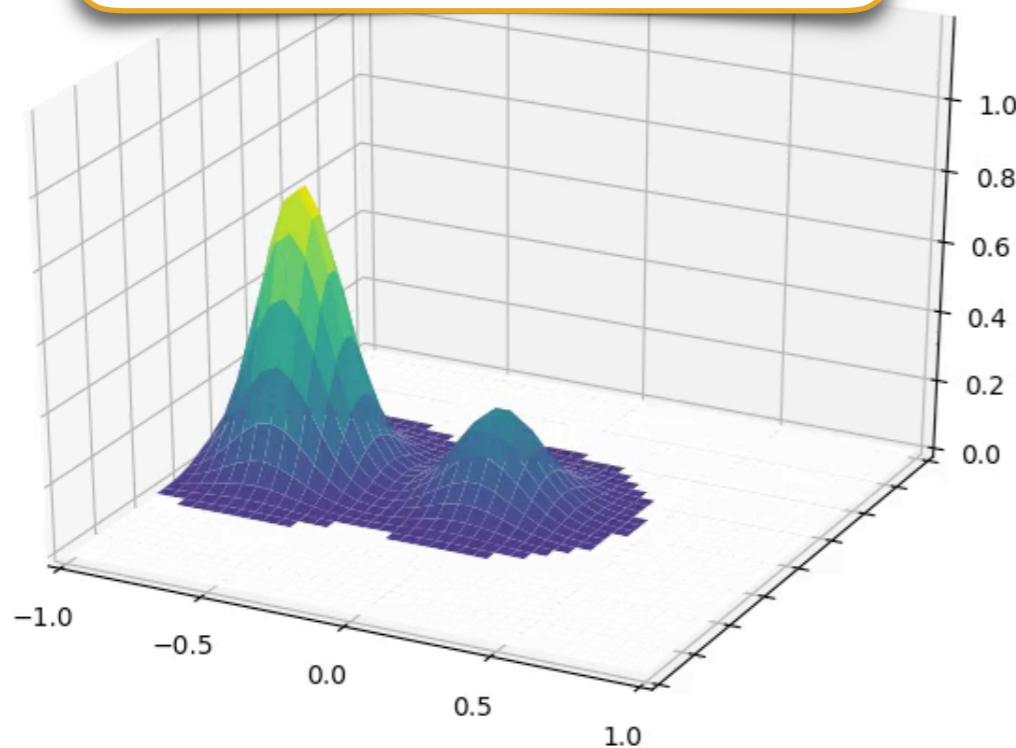
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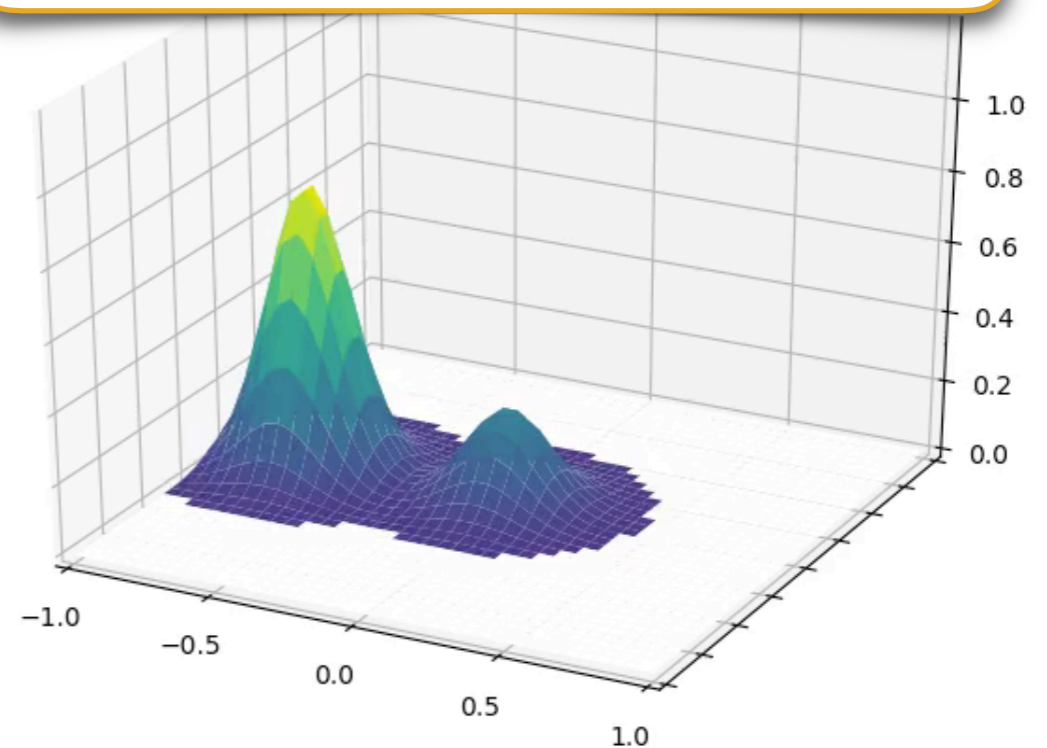
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gradient flow in the Wasserstein metric

Examples:

energy functional	gradient flow
$E(\rho) = \int \rho \log \rho$	$\frac{d}{dt} \rho = \Delta \rho$
$E(\rho) = \frac{1}{m-1} \int \rho^m$	$\frac{d}{dt} \rho = \Delta \rho^m$
$E(\rho) = \int V \rho$	$\frac{d}{dt} \rho = \nabla \cdot (\nabla V \rho)$
$E(\rho) = \int (K * \rho) \rho$	$\frac{d}{dt} \rho = \nabla \cdot (\nabla (K * \rho) \rho)$

All Wasserstein gradient flows are of the form

$$\frac{d}{dt} \rho + \nabla \cdot (v \rho) = 0$$

continuity equation

gradient flow in the Wasserstein metric

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continuity equation

$$v = -\nabla \frac{\partial E}{\partial \rho}$$

gradient flow in the Wasserstein metric

aggregation, drift, and degenerate diffusion:

$$\frac{d}{dt}\rho = \underbrace{\nabla \cdot ((\nabla K * \rho)\rho)}_{\text{self interaction}} + \underbrace{\nabla \cdot (\nabla V \rho)}_{\text{drift}} + \underbrace{\Delta \rho^m}_{\text{diffusion}}$$

$K, V : \mathbb{R}^d \rightarrow \mathbb{R}$, and $m \geq 1$

$$E(\rho) = \frac{1}{2} \int K * \rho d\rho + \int V d\rho + \frac{1}{m-1} \int \rho^m$$

interaction kernels:

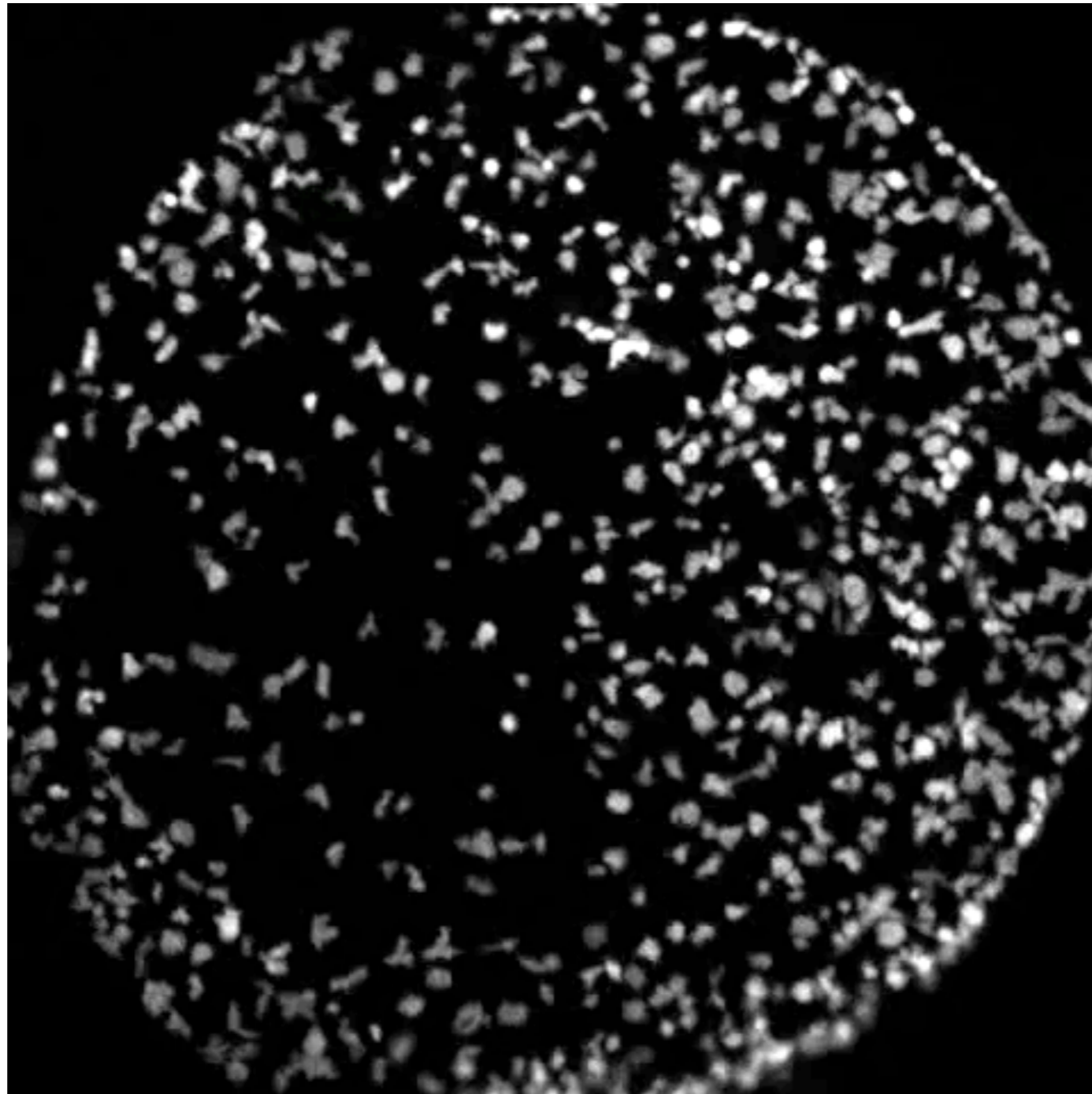
- granular media: $K(x) = |x|^3$
- swarming: $K(x) = |x|^a/a - |x|^b/b$, $-d < b < a$
- chemotaxis: $K(x) = \begin{cases} \frac{1}{2\pi} \log |x| & \text{if } d = 2, \\ C_d |x|^{2-d} & \text{otherwise.} \end{cases}$

degenerate diffusion:

$$\Delta \rho^m = \nabla \cdot (\underbrace{m \rho^{m-1}}_D \nabla \rho)$$

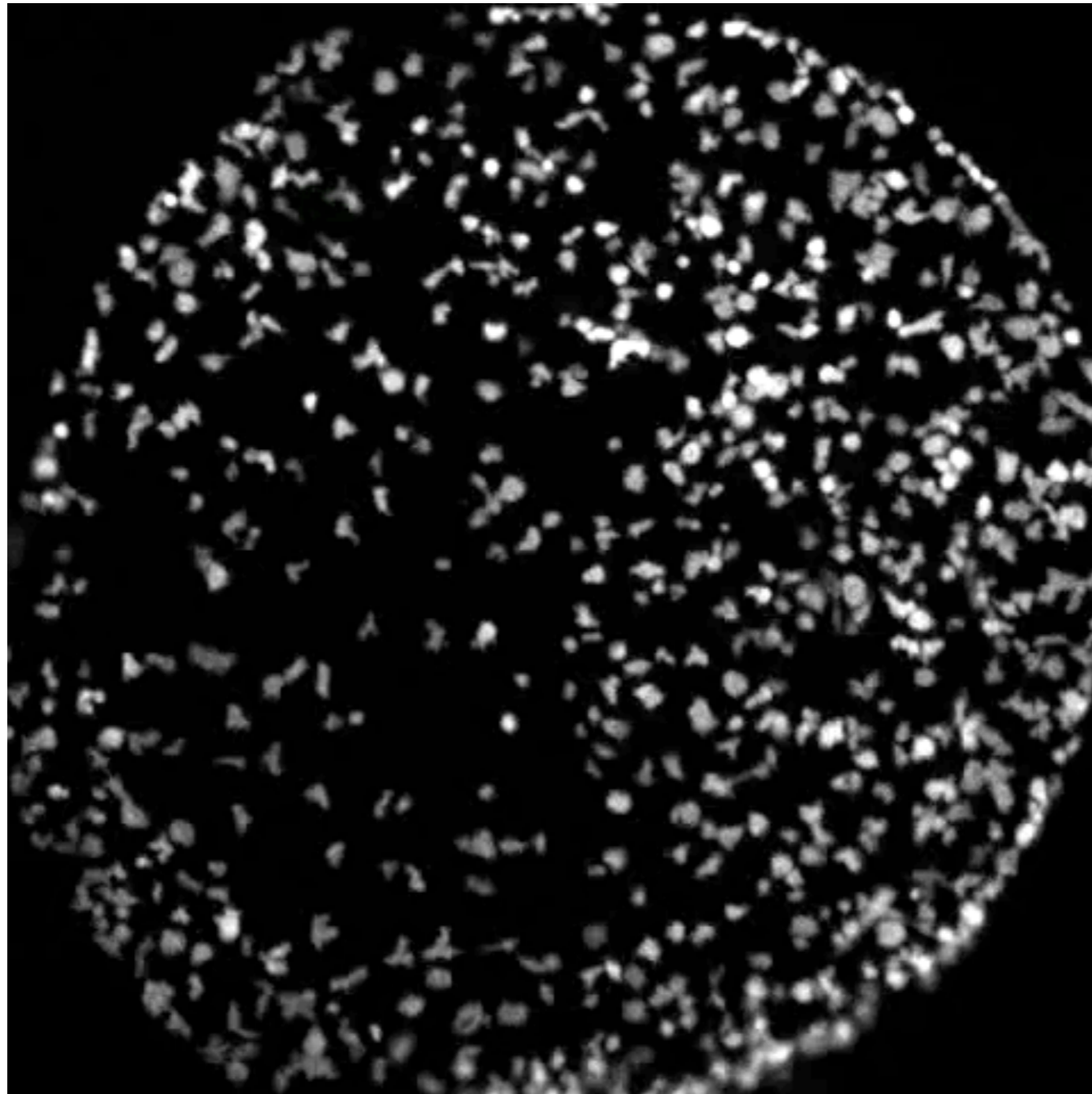
biological chemotaxis

a colony of slime mold [Gregor, et. al]



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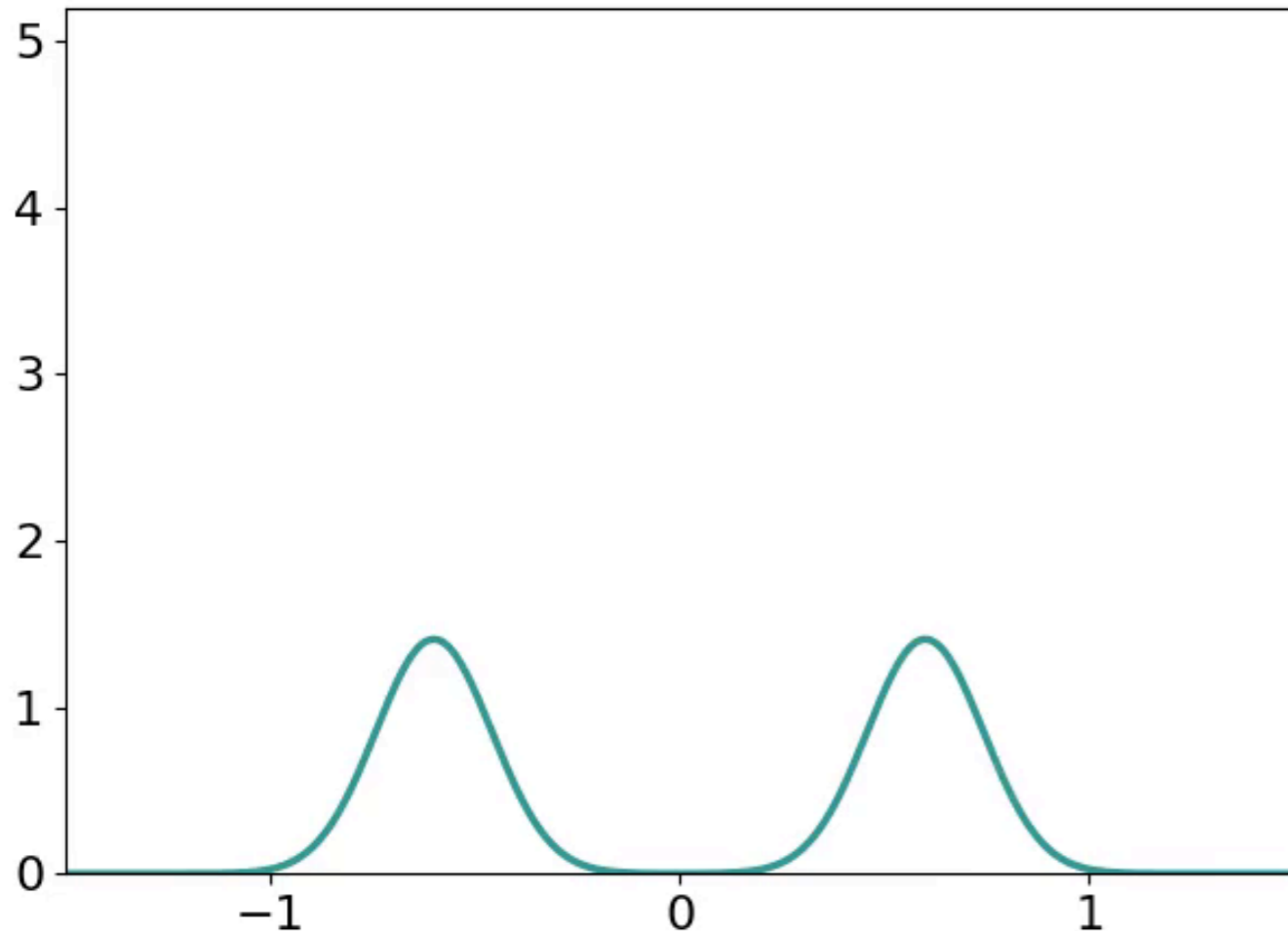


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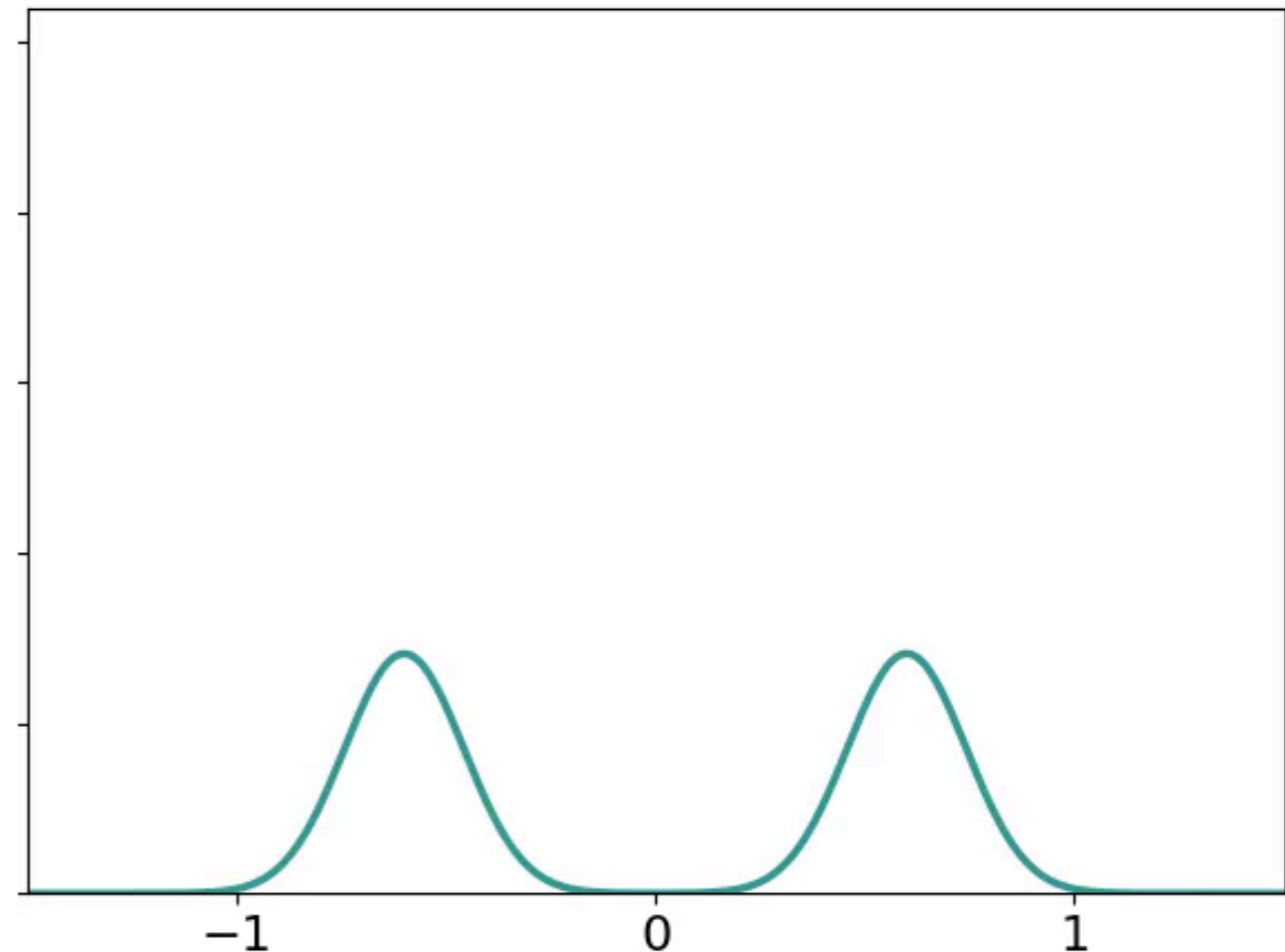
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$$K(x) = |x|$$



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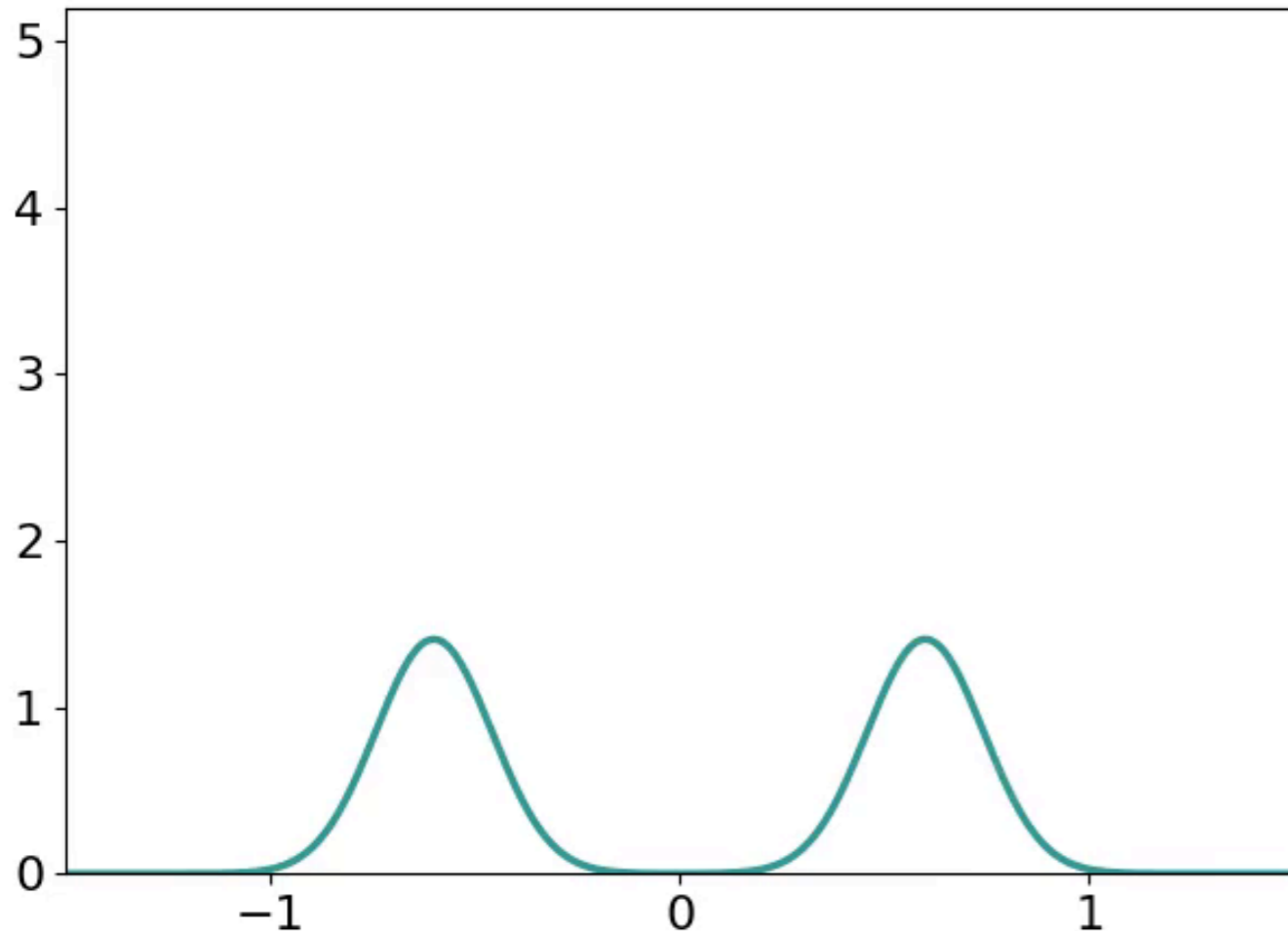


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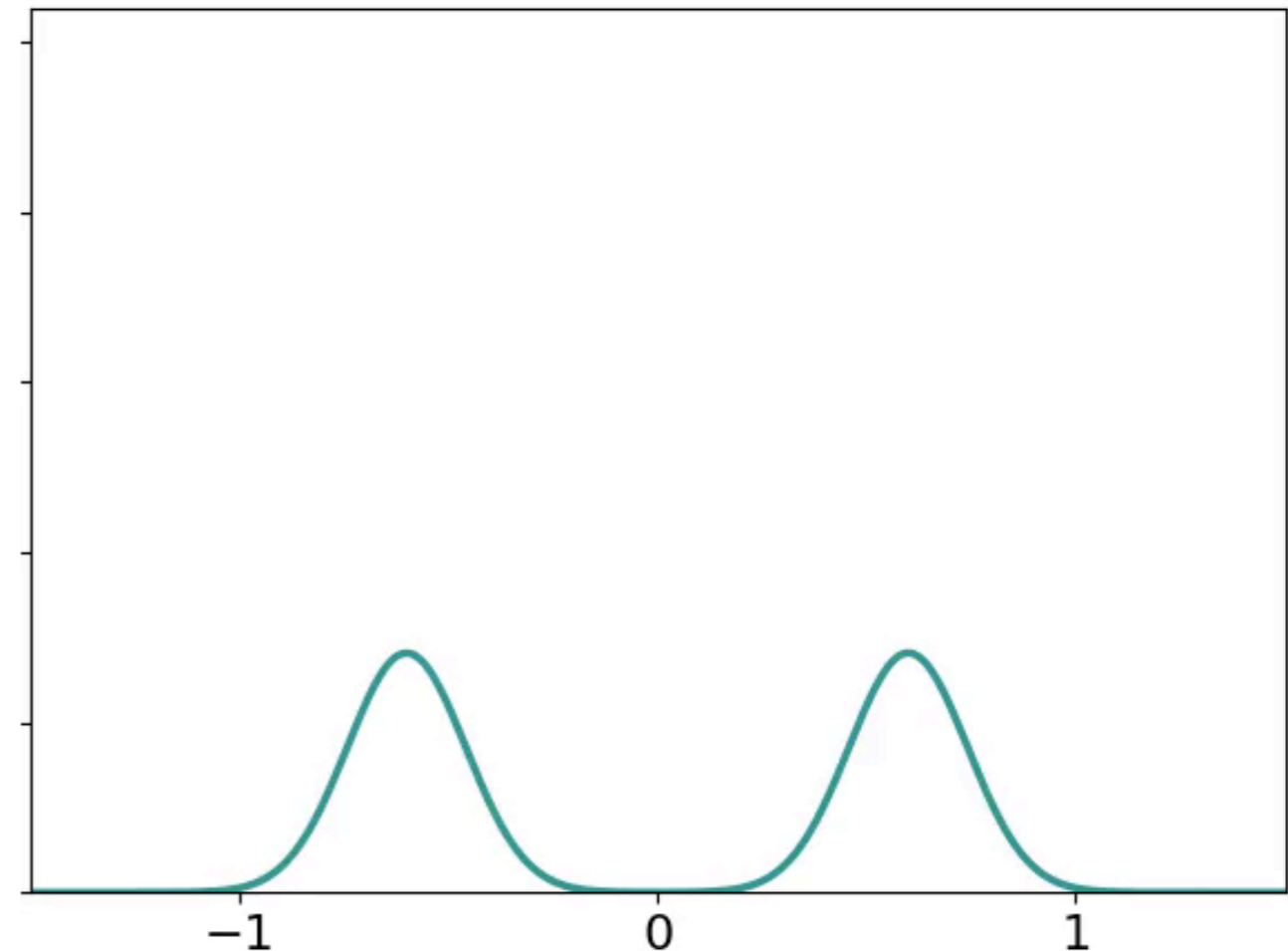
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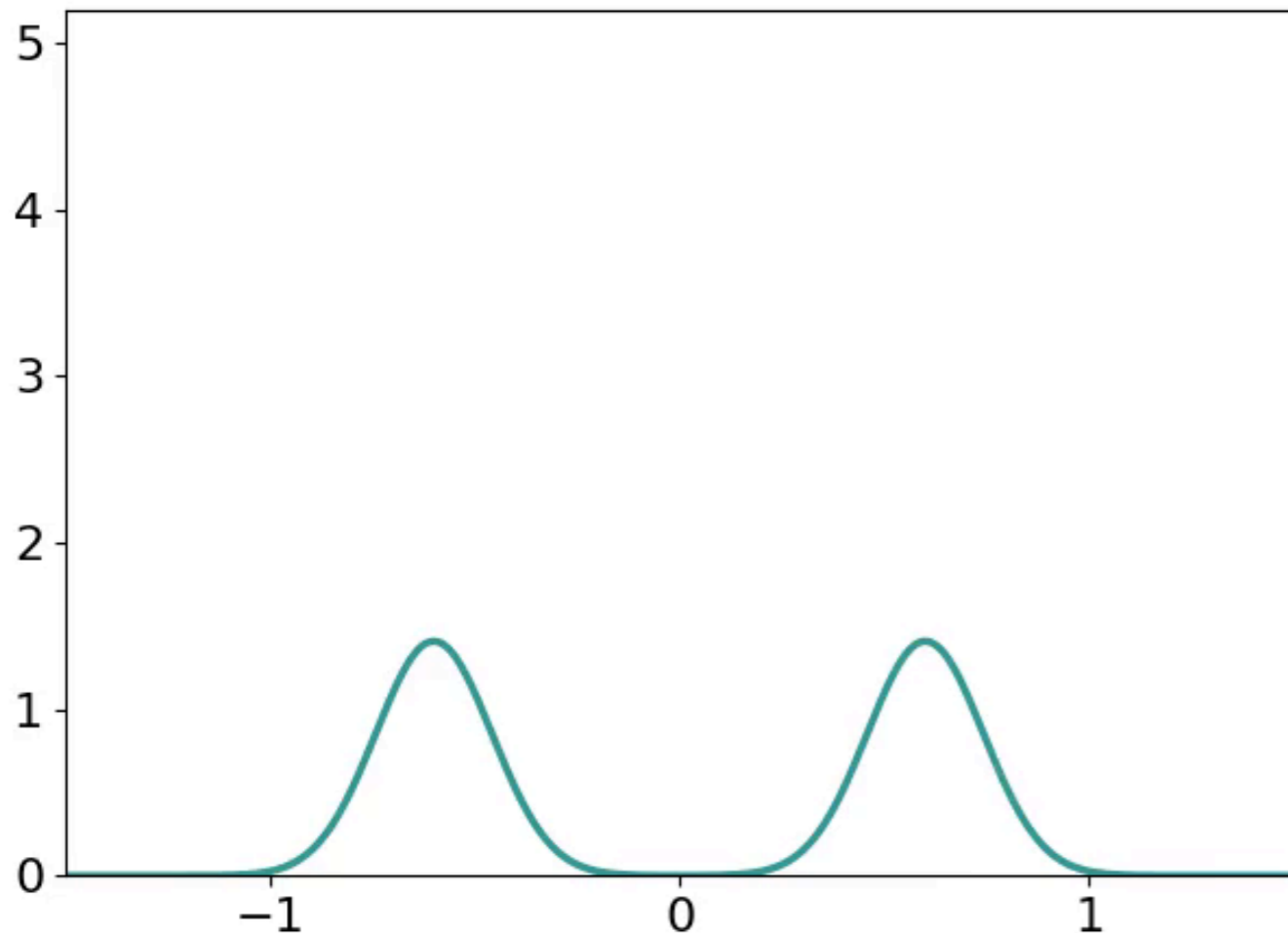


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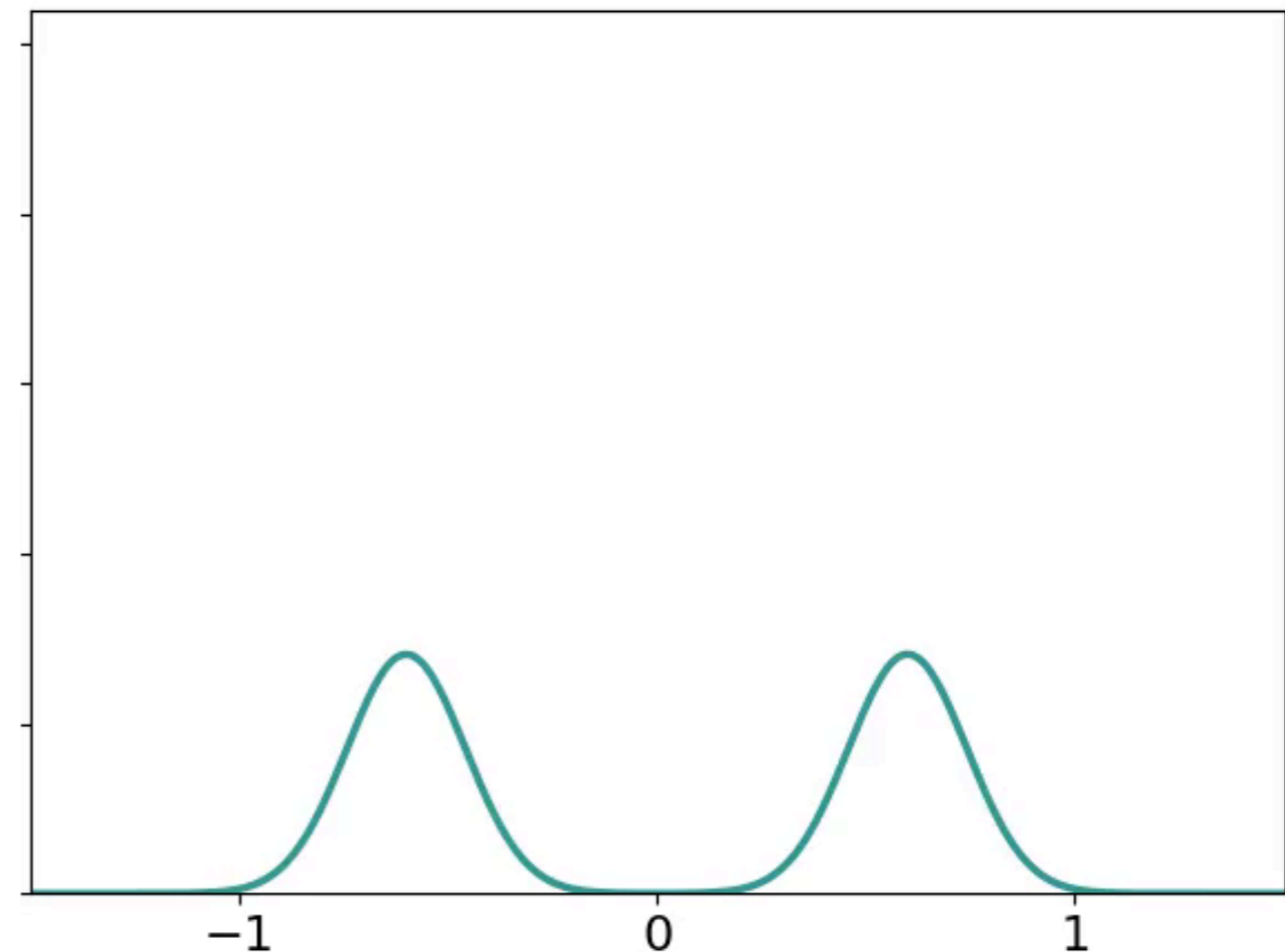
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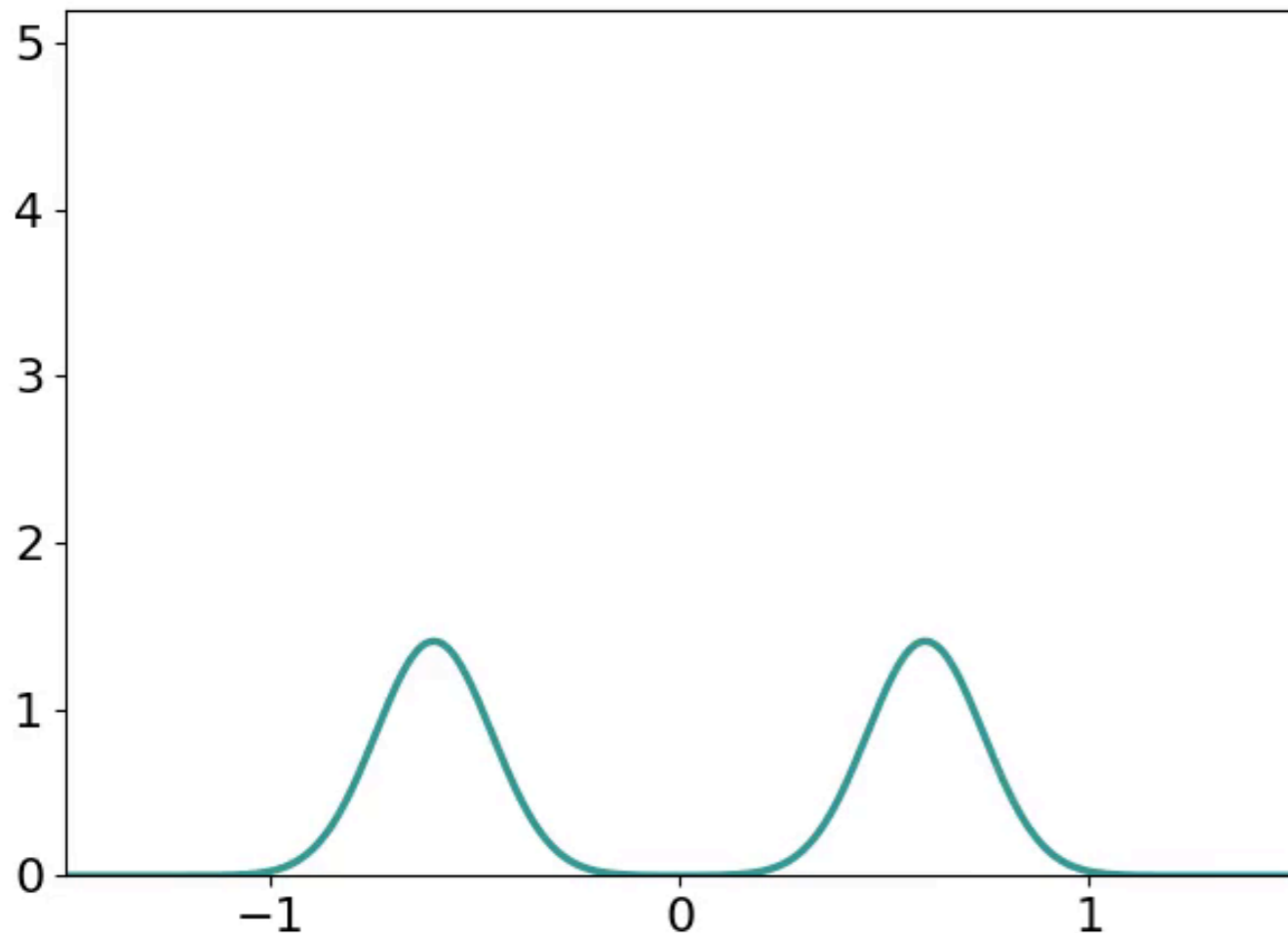


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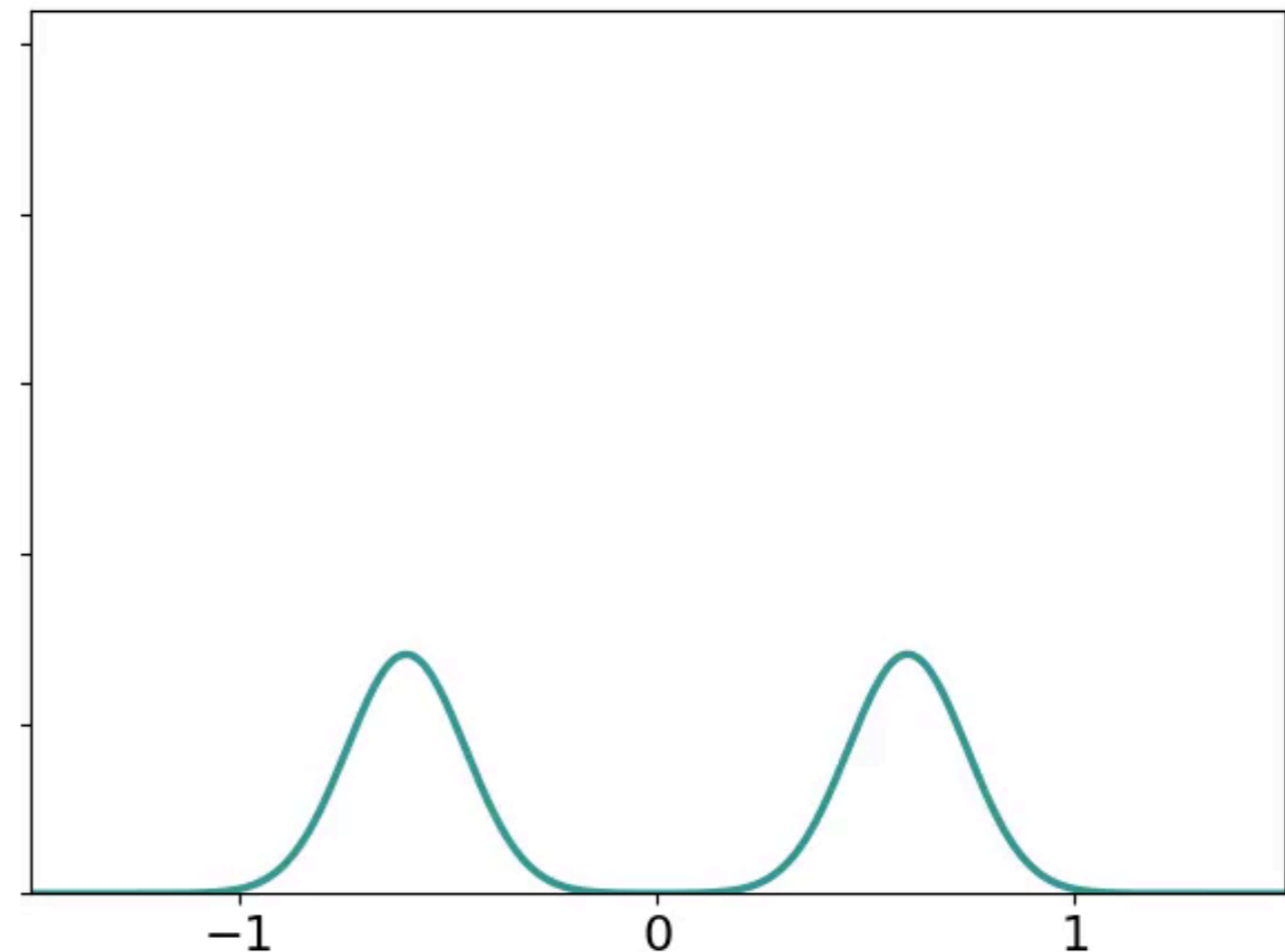
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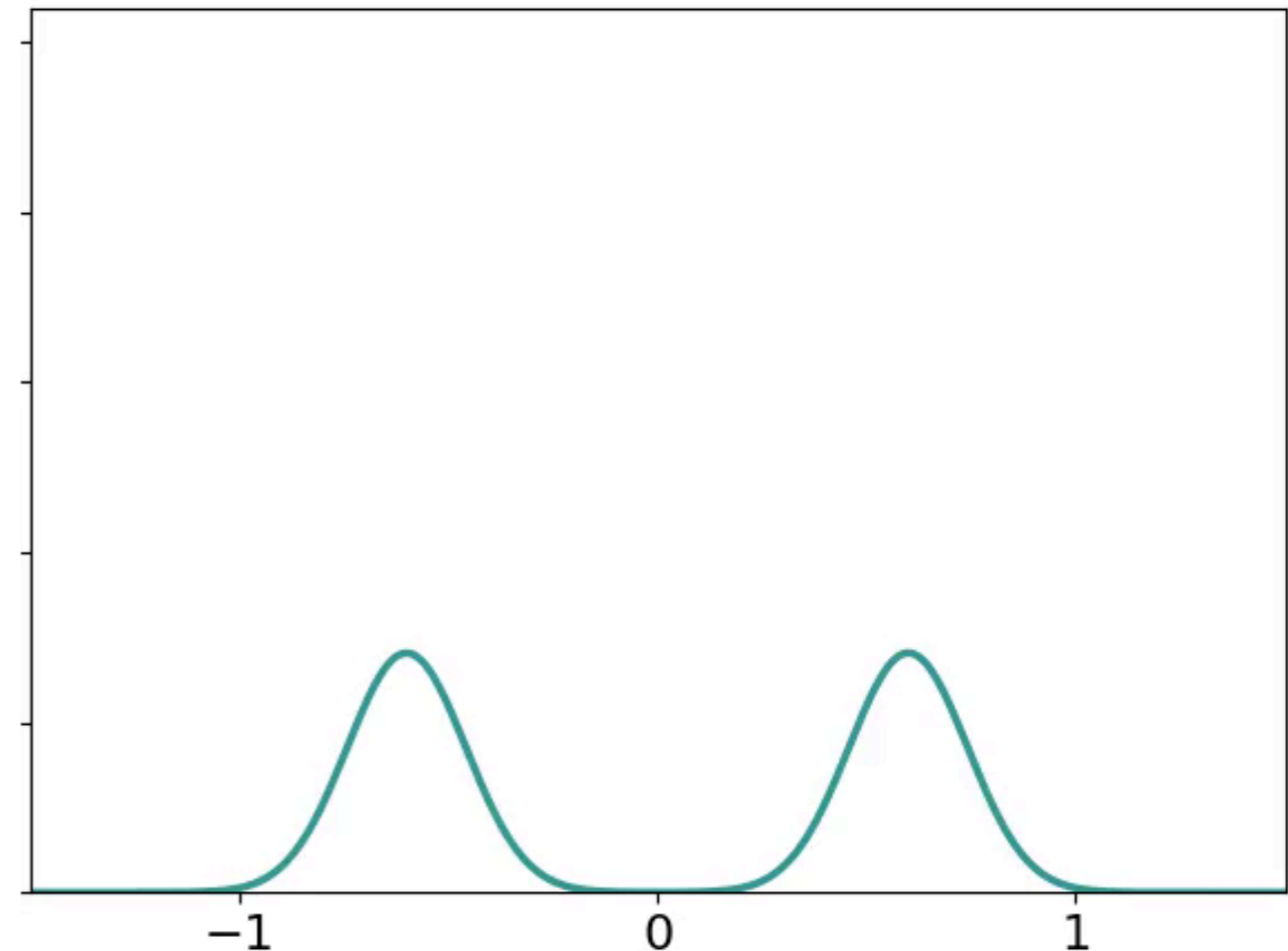
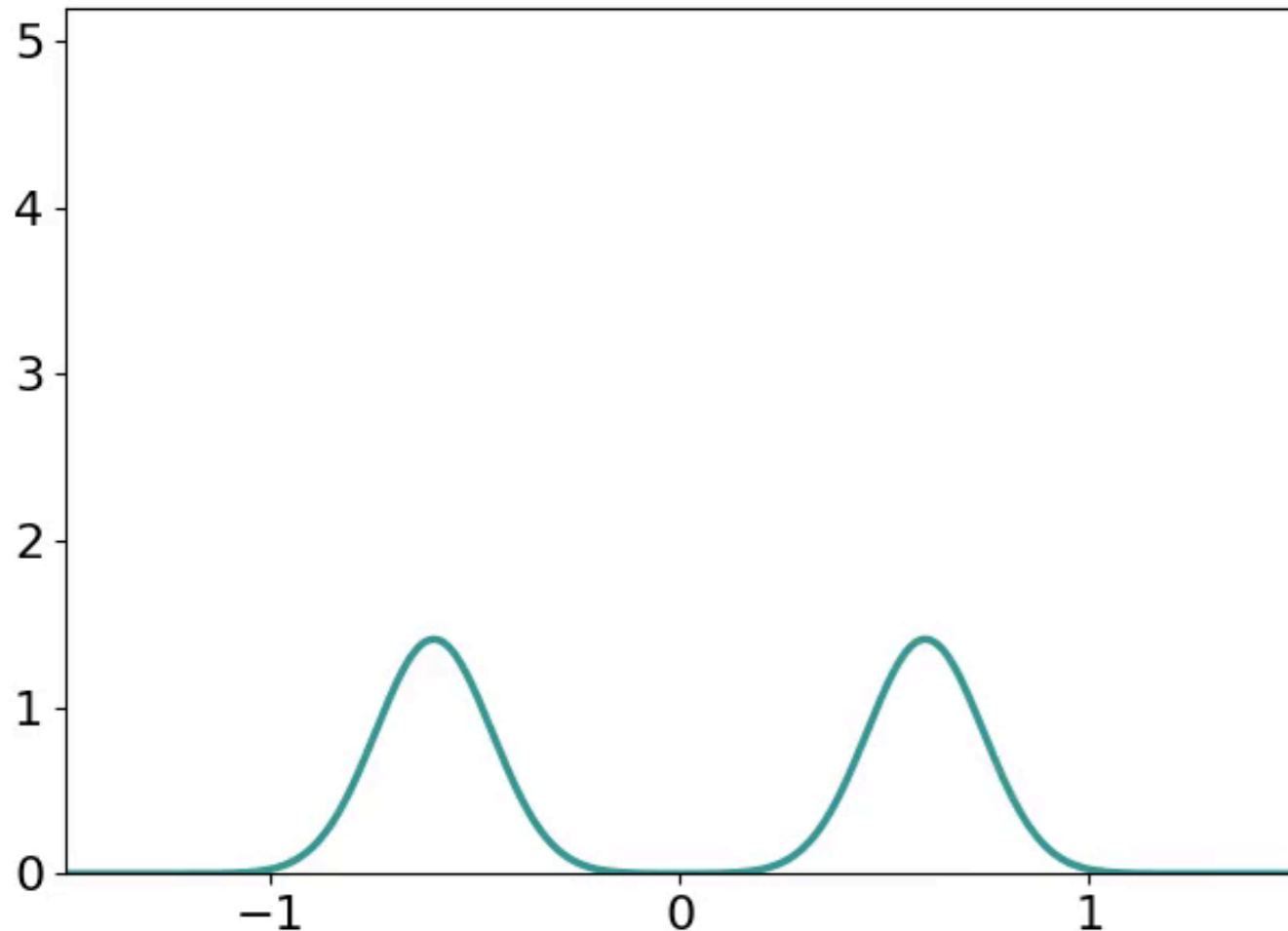


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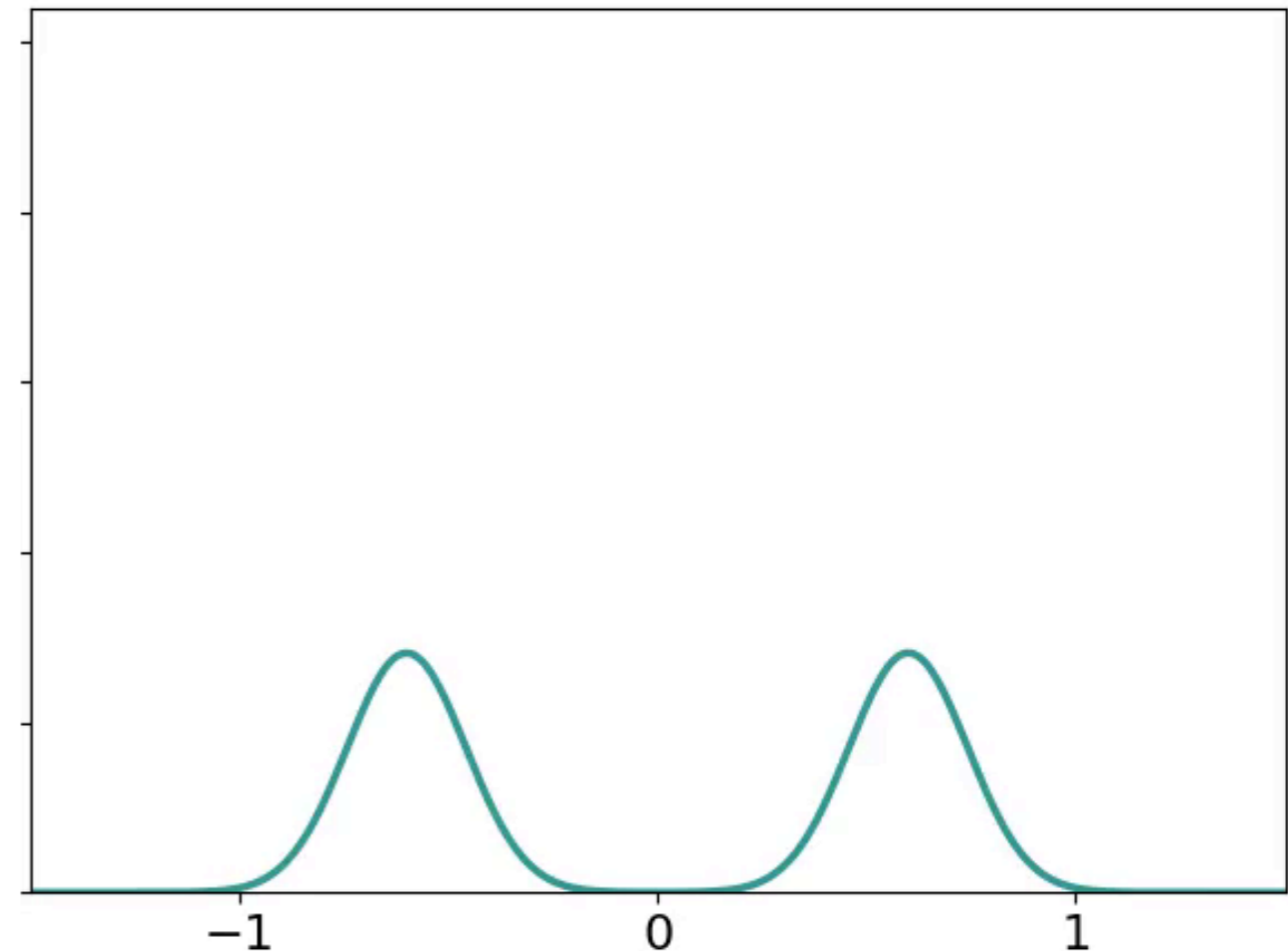
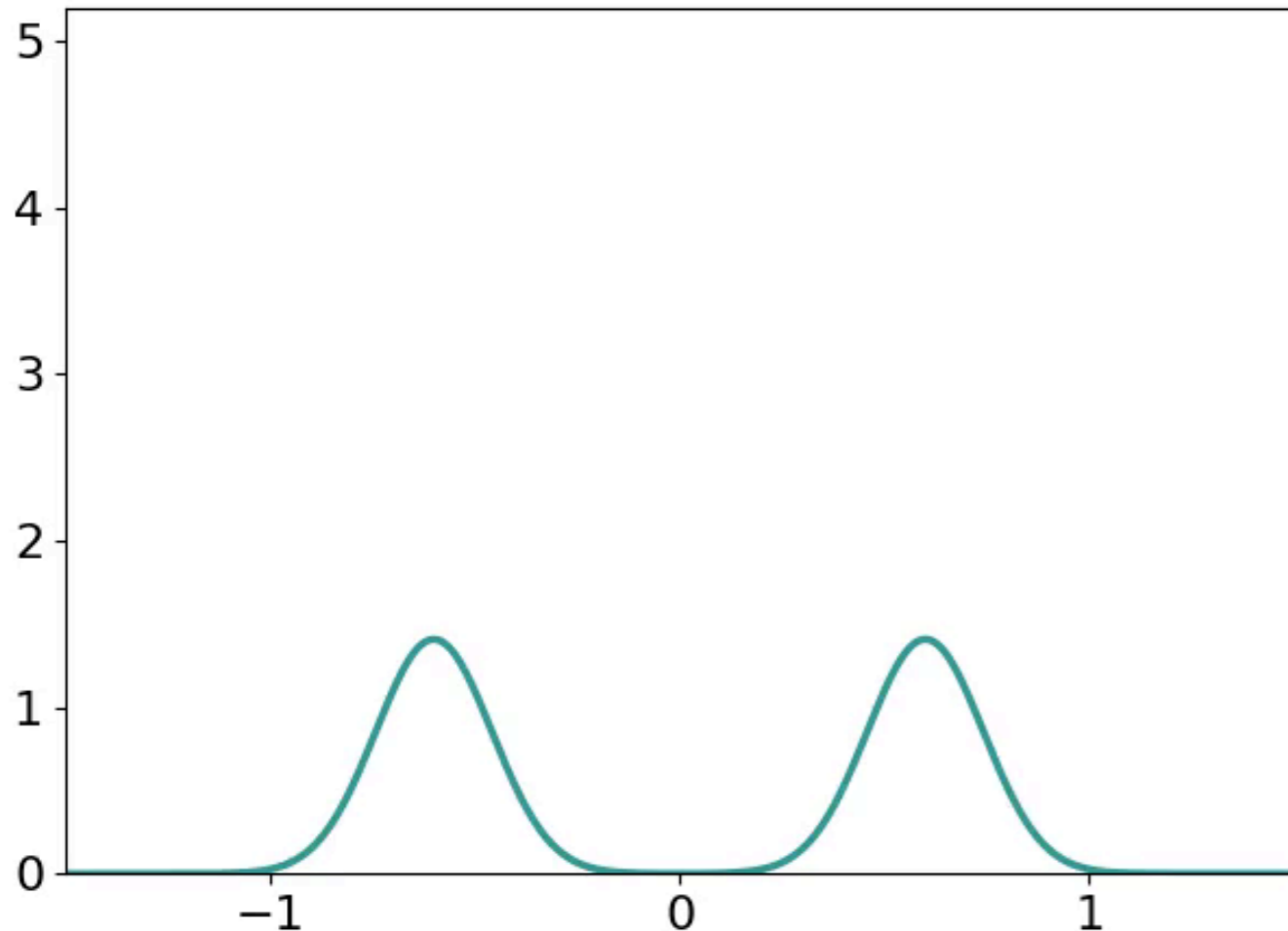


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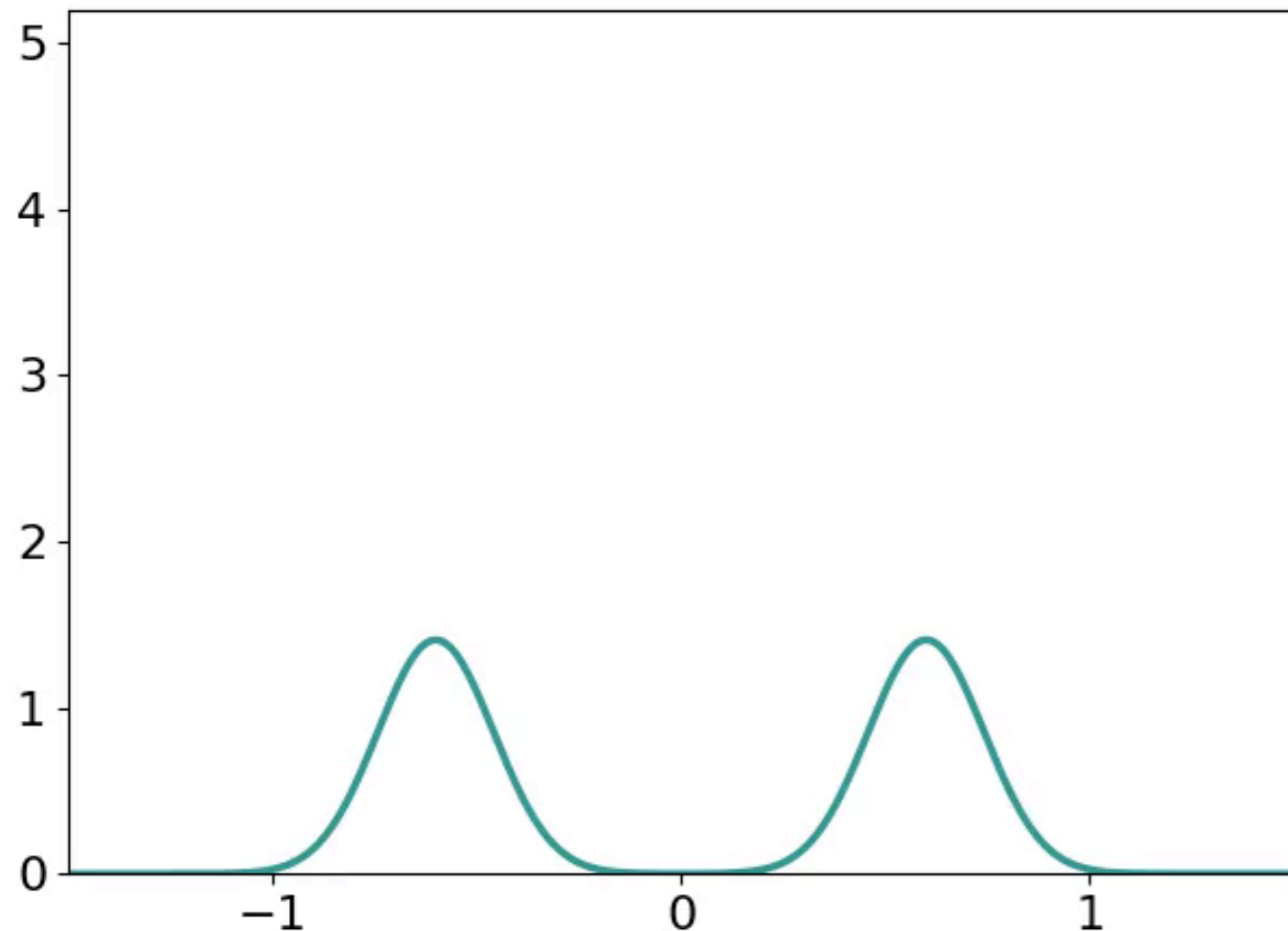


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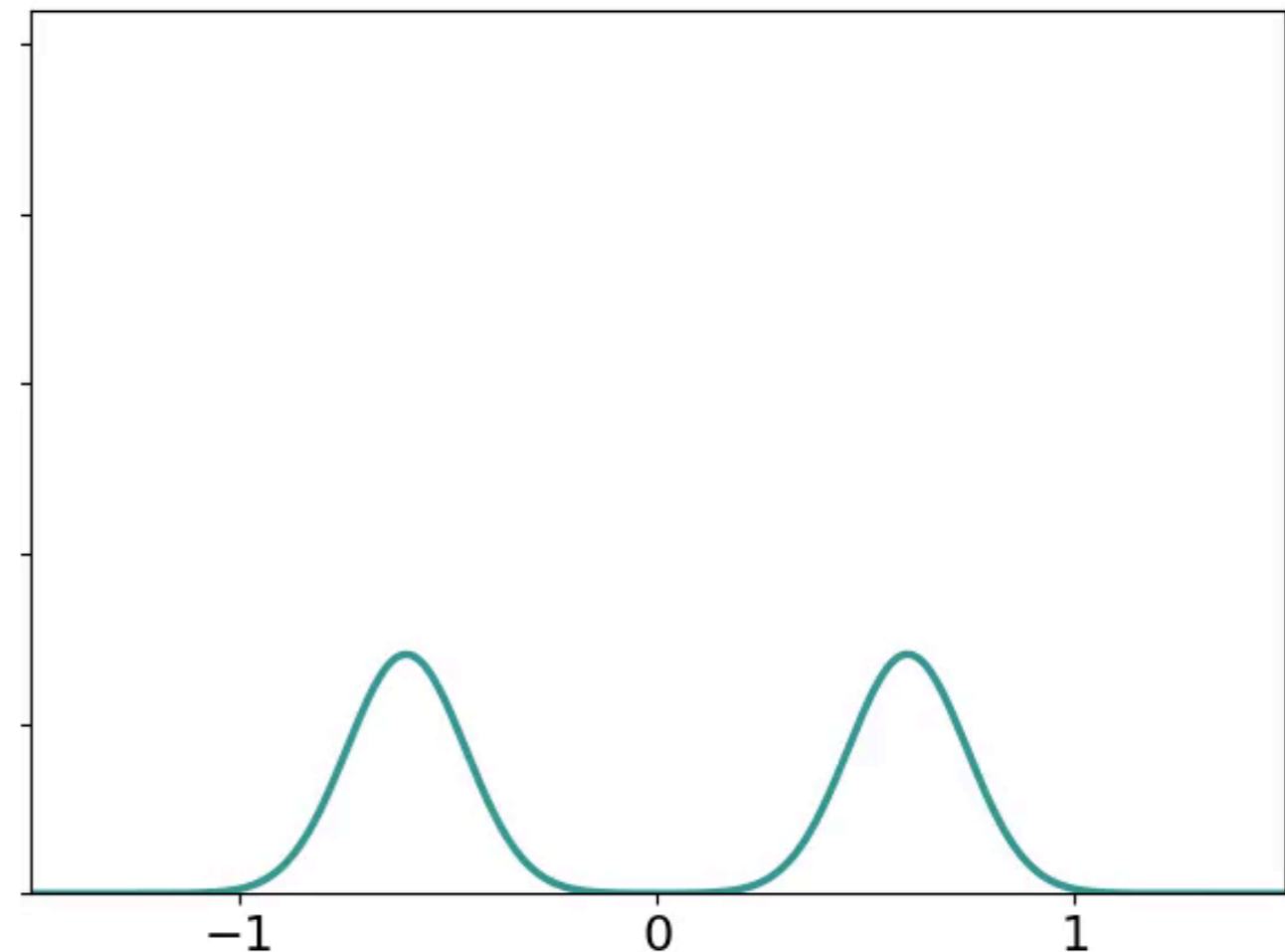
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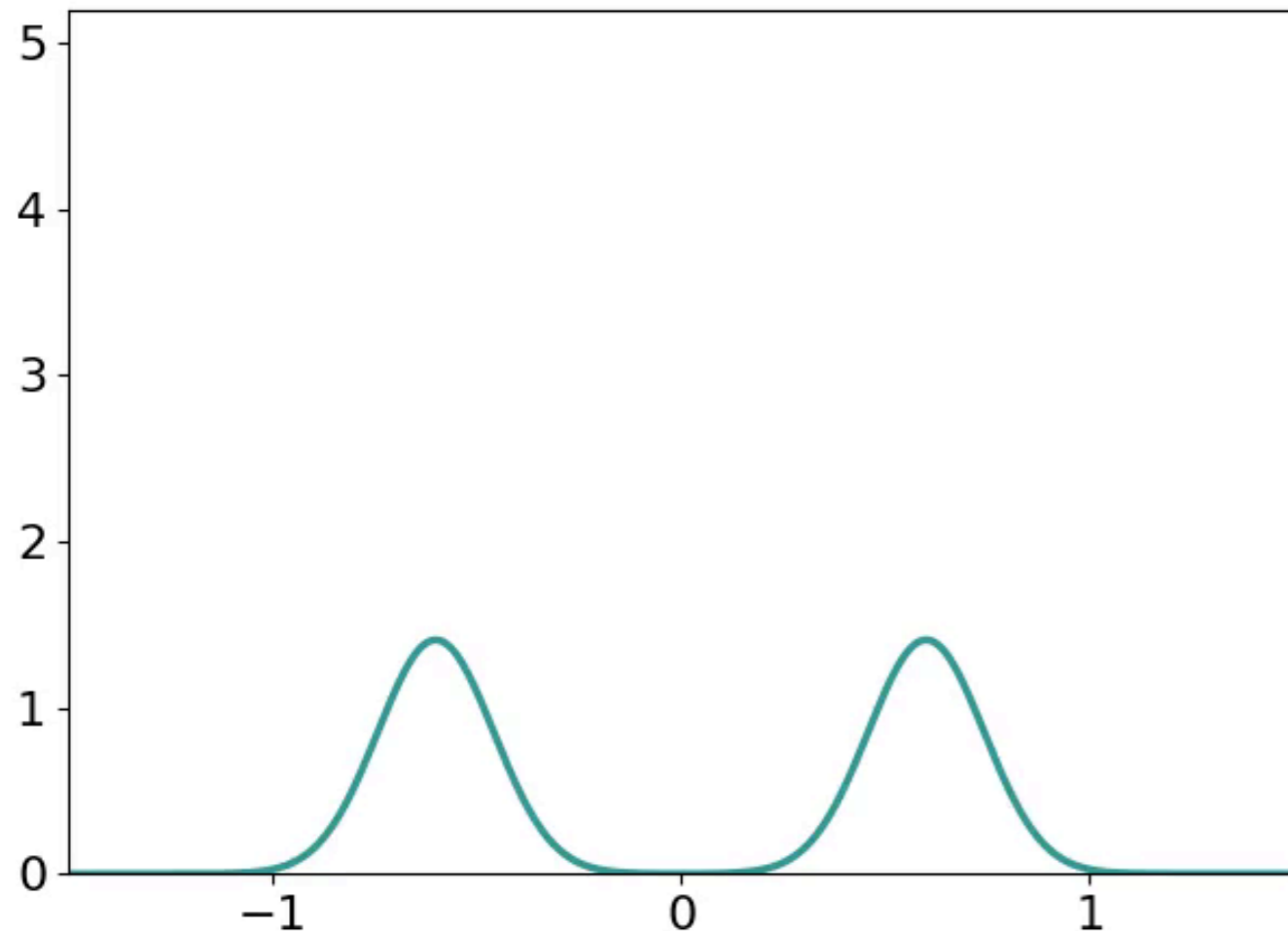


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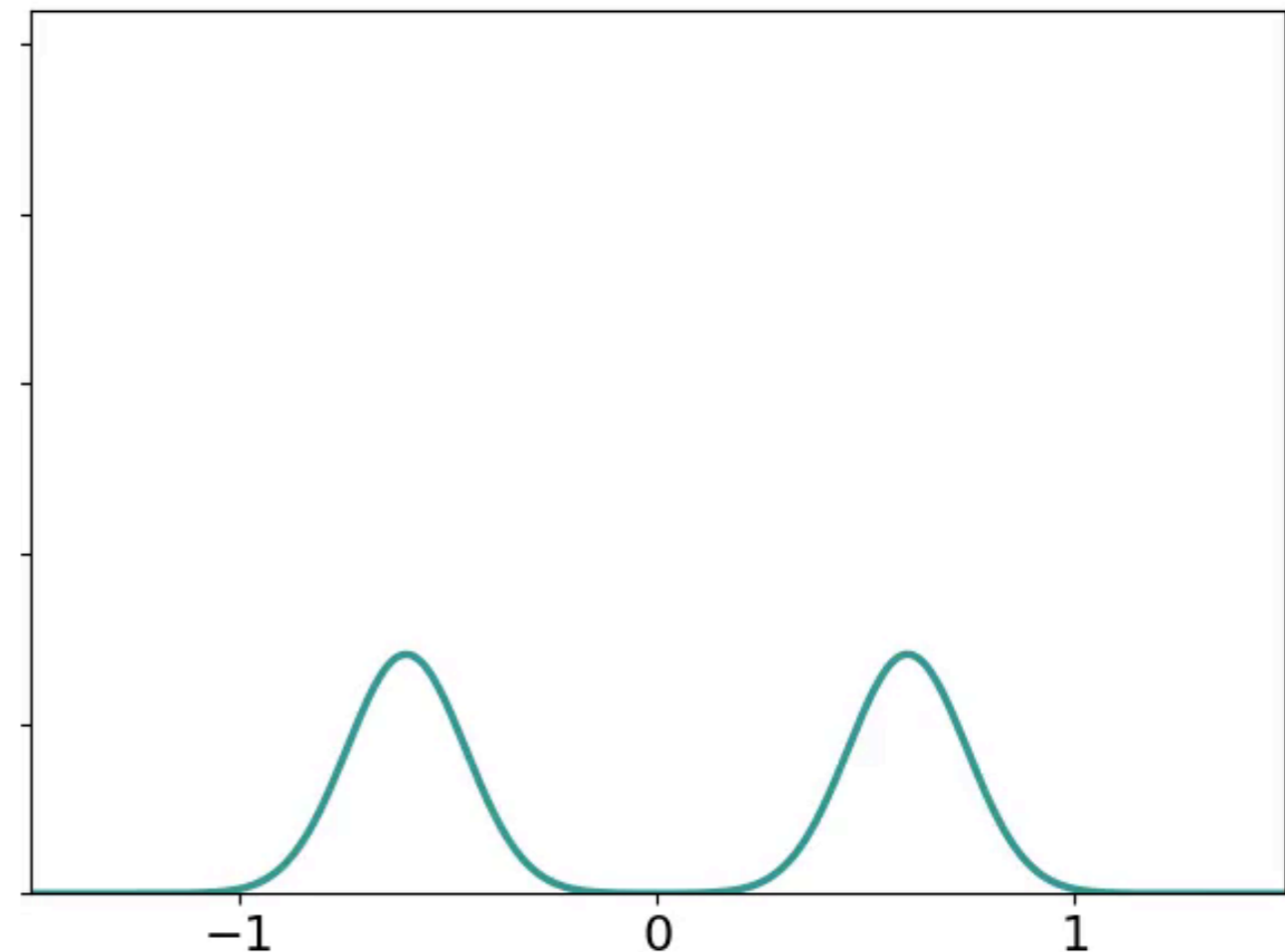
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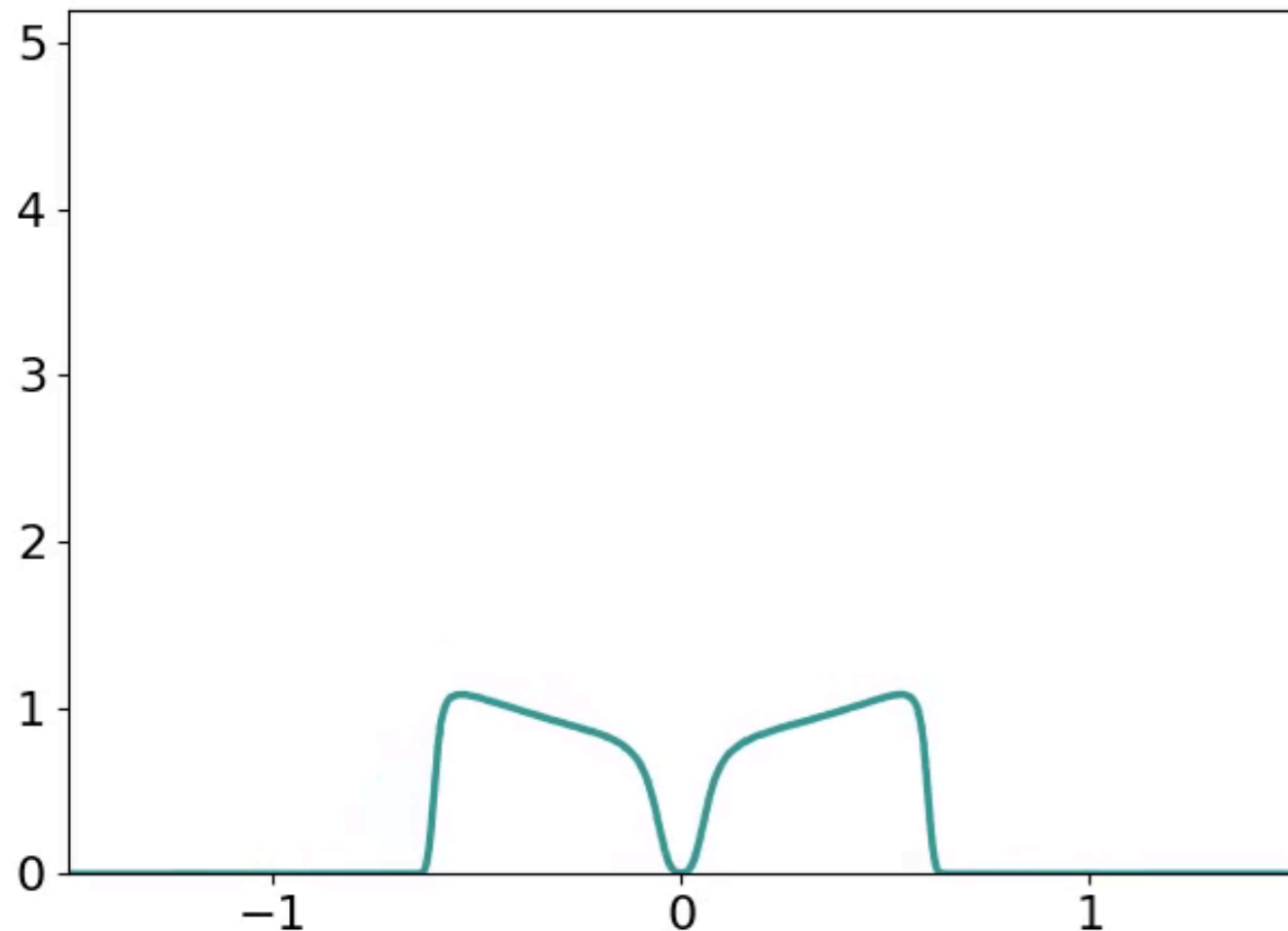


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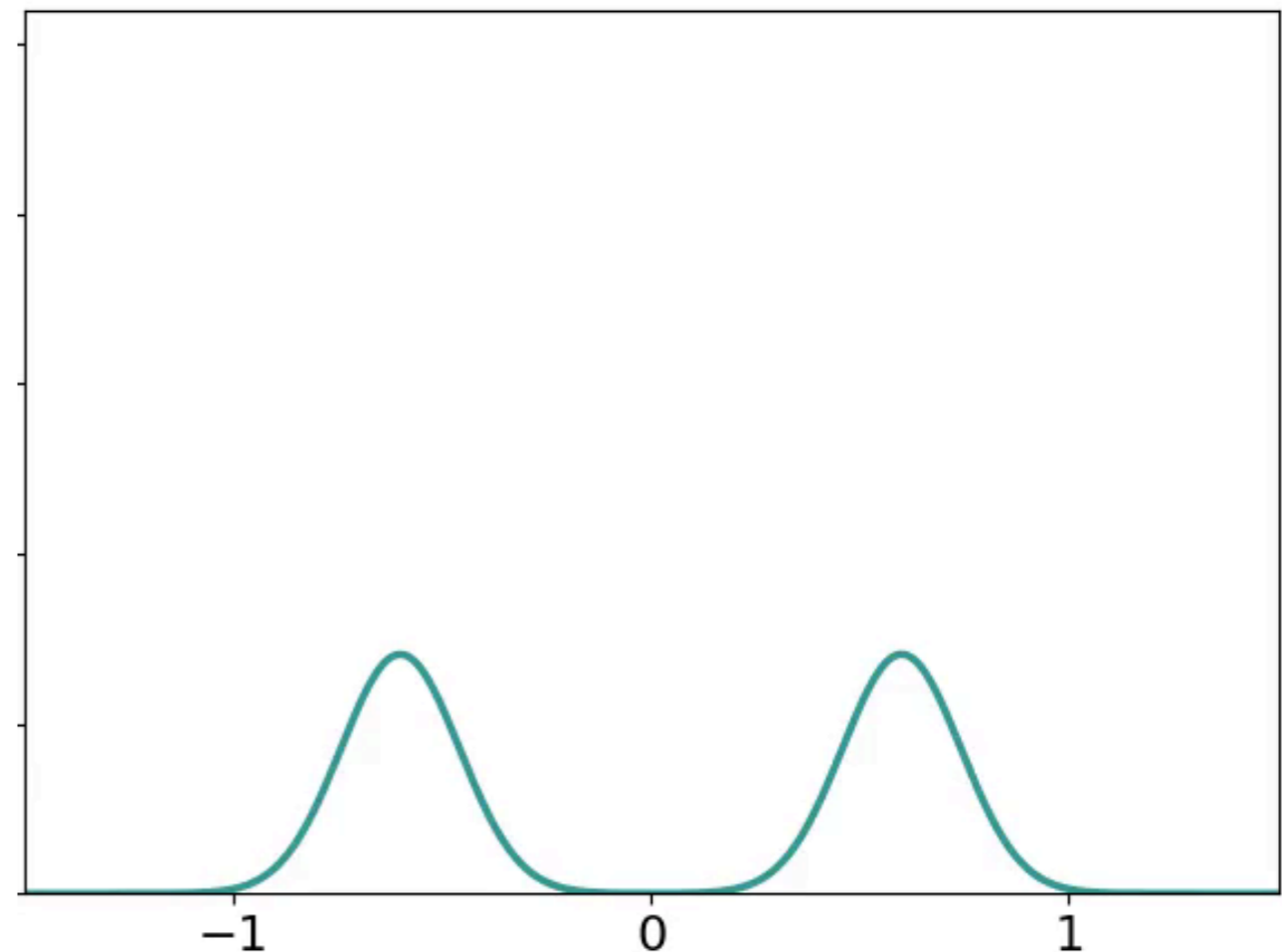
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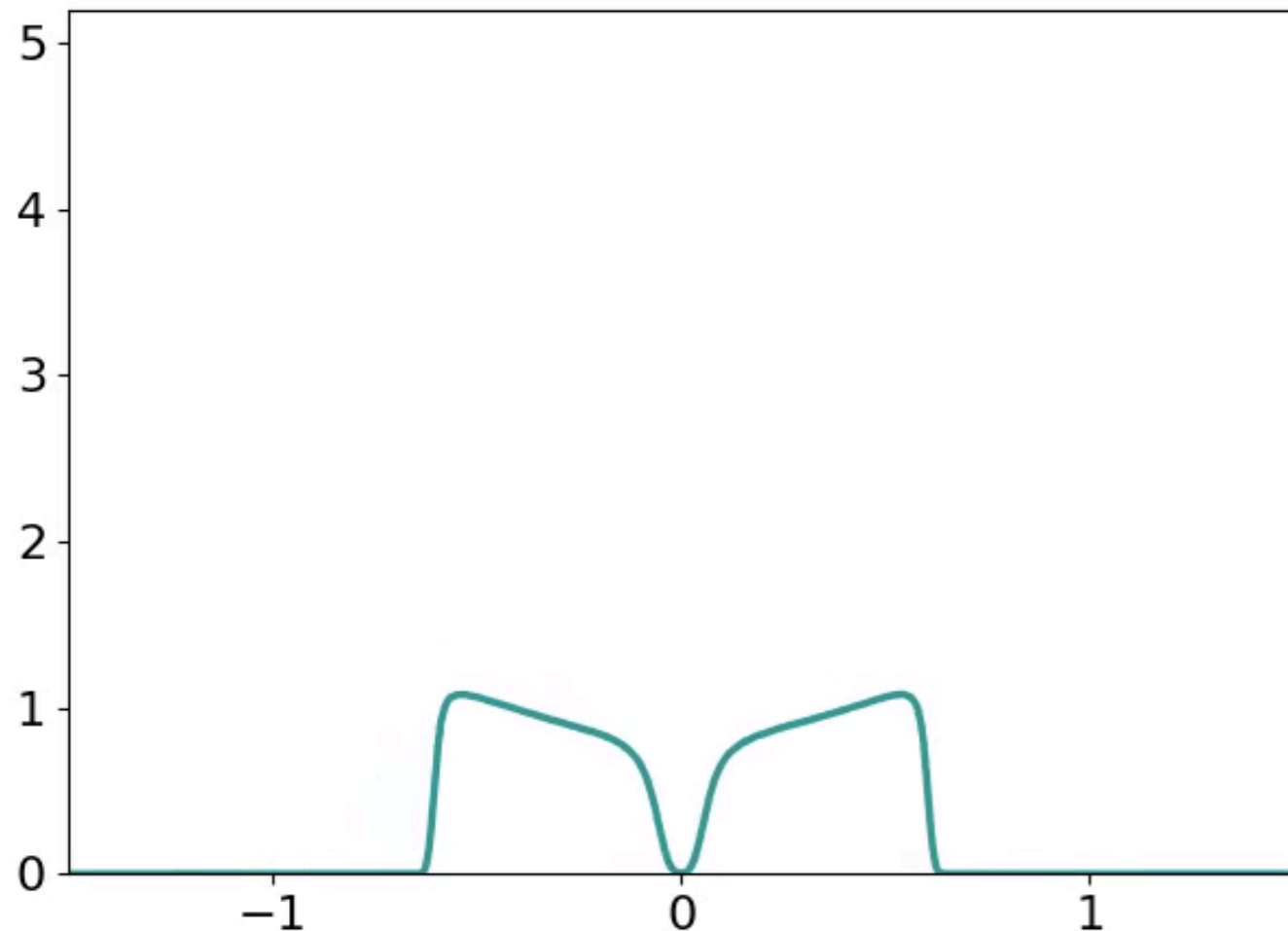


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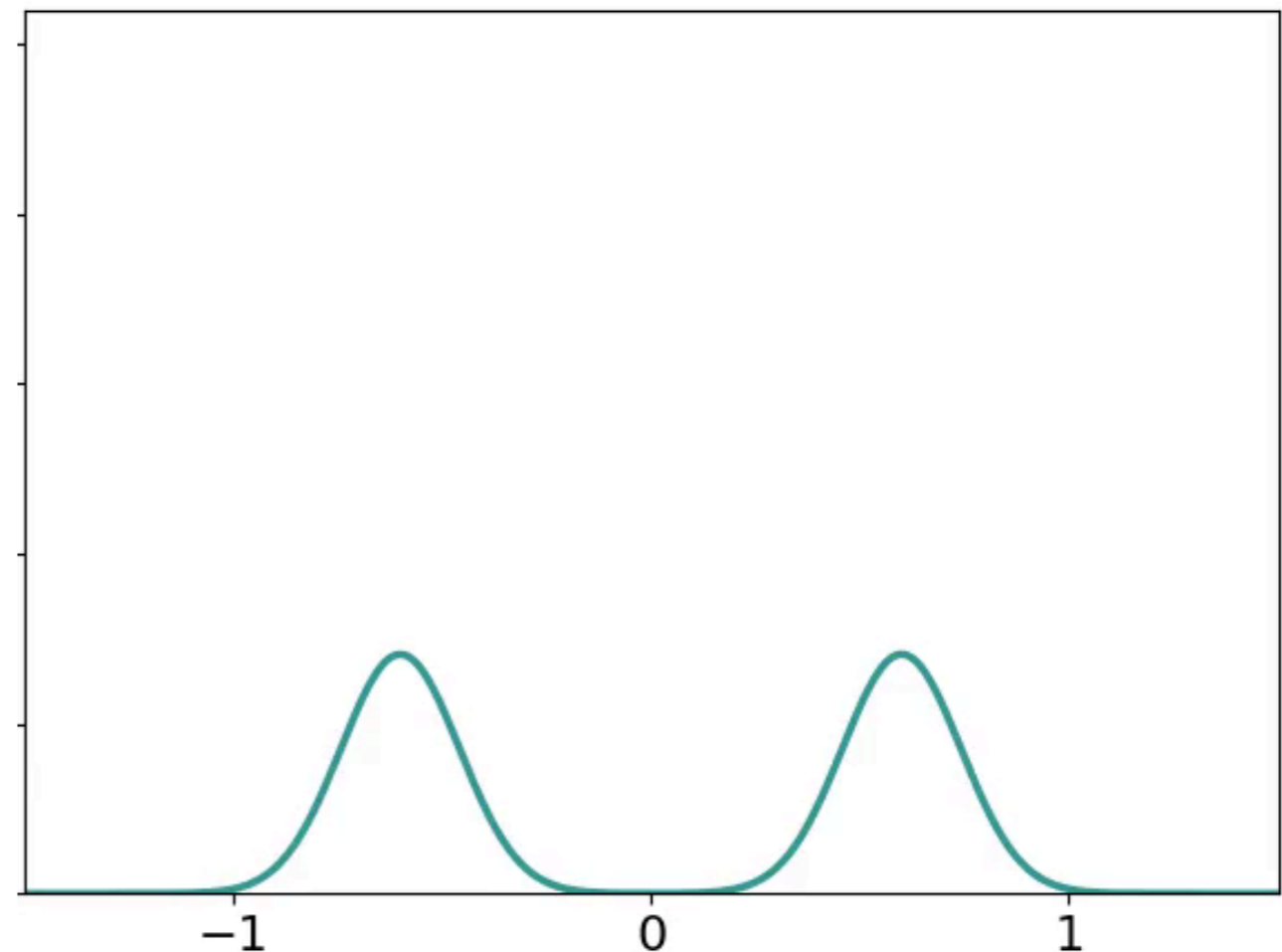
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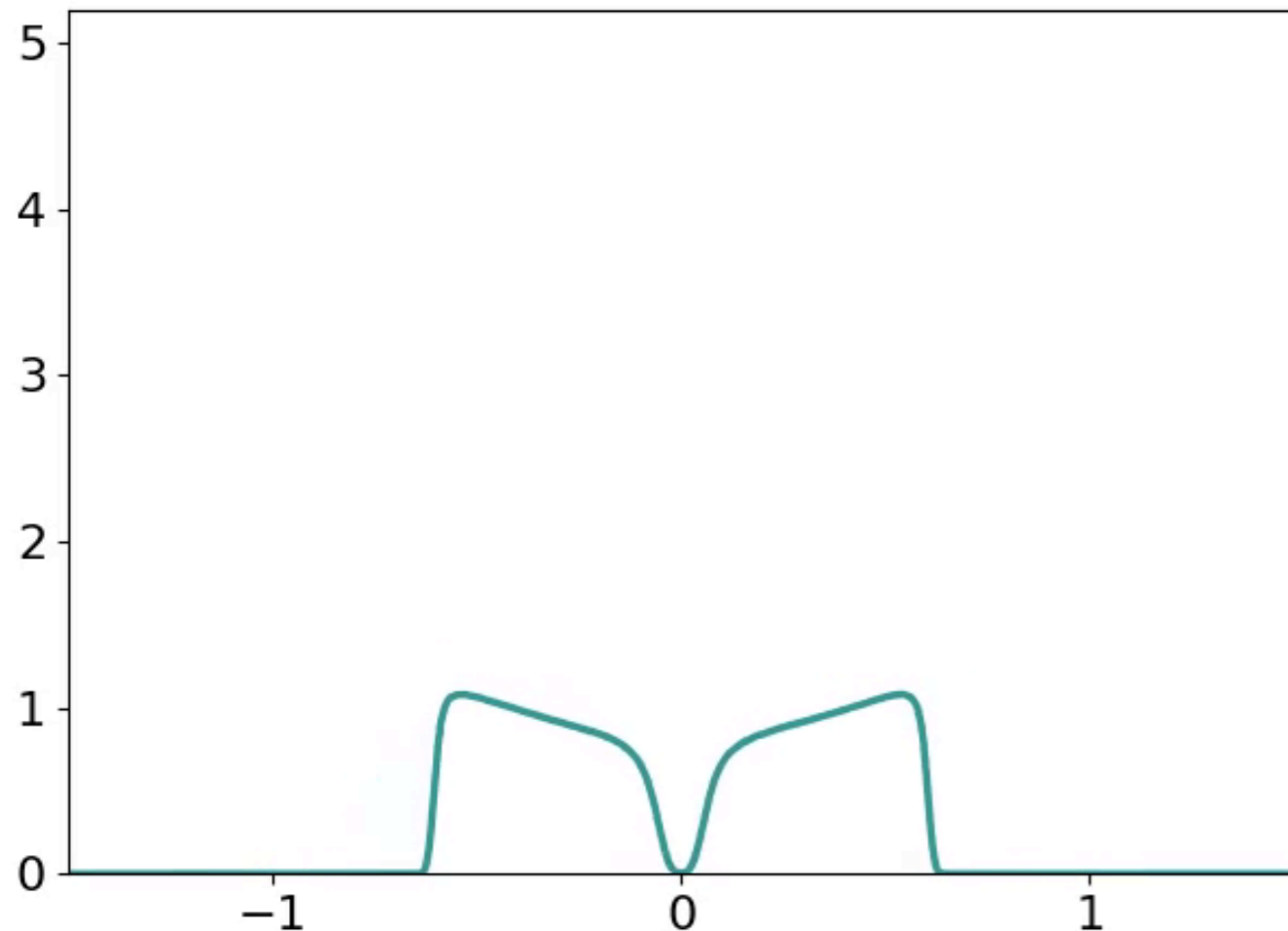


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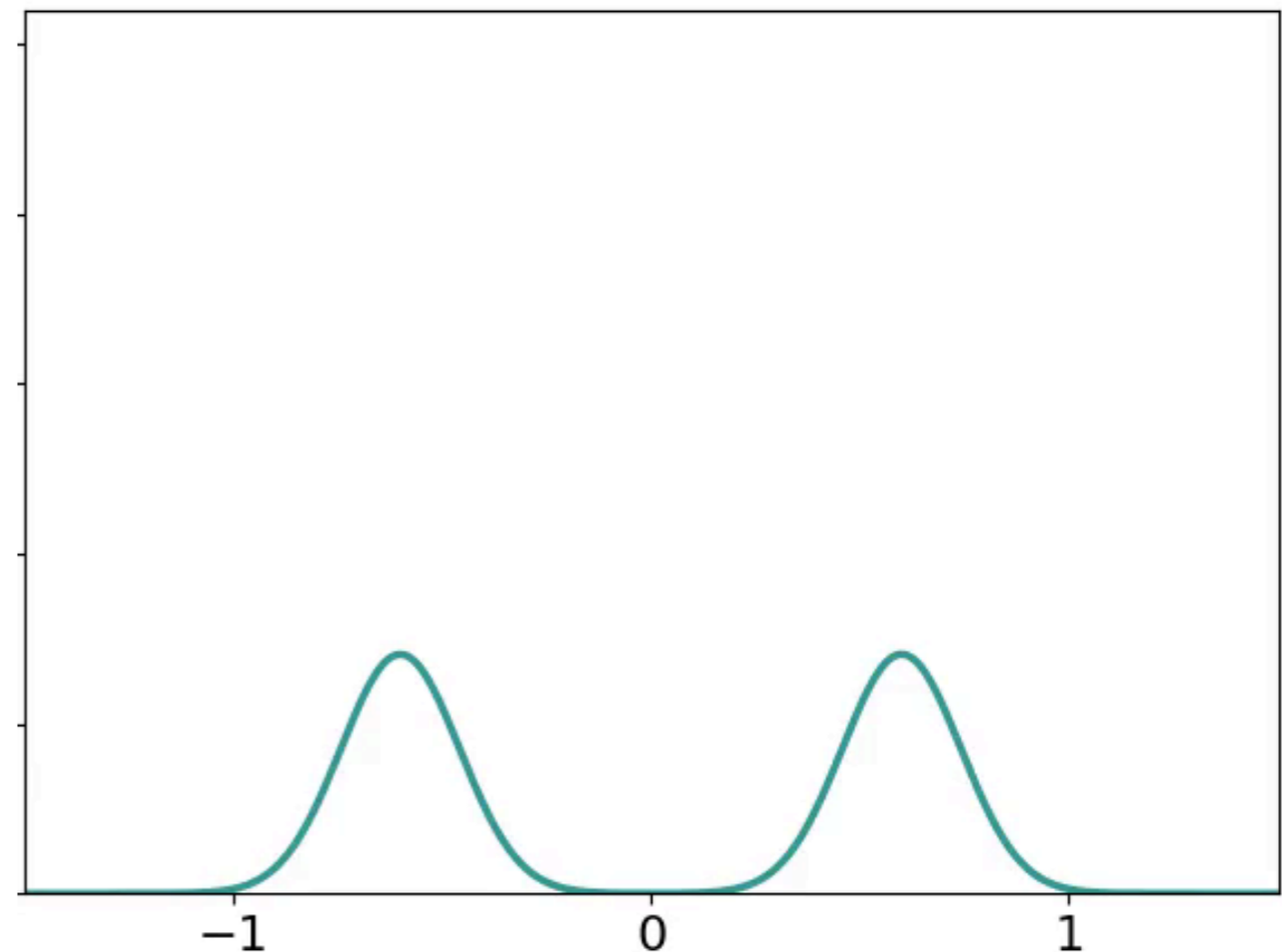
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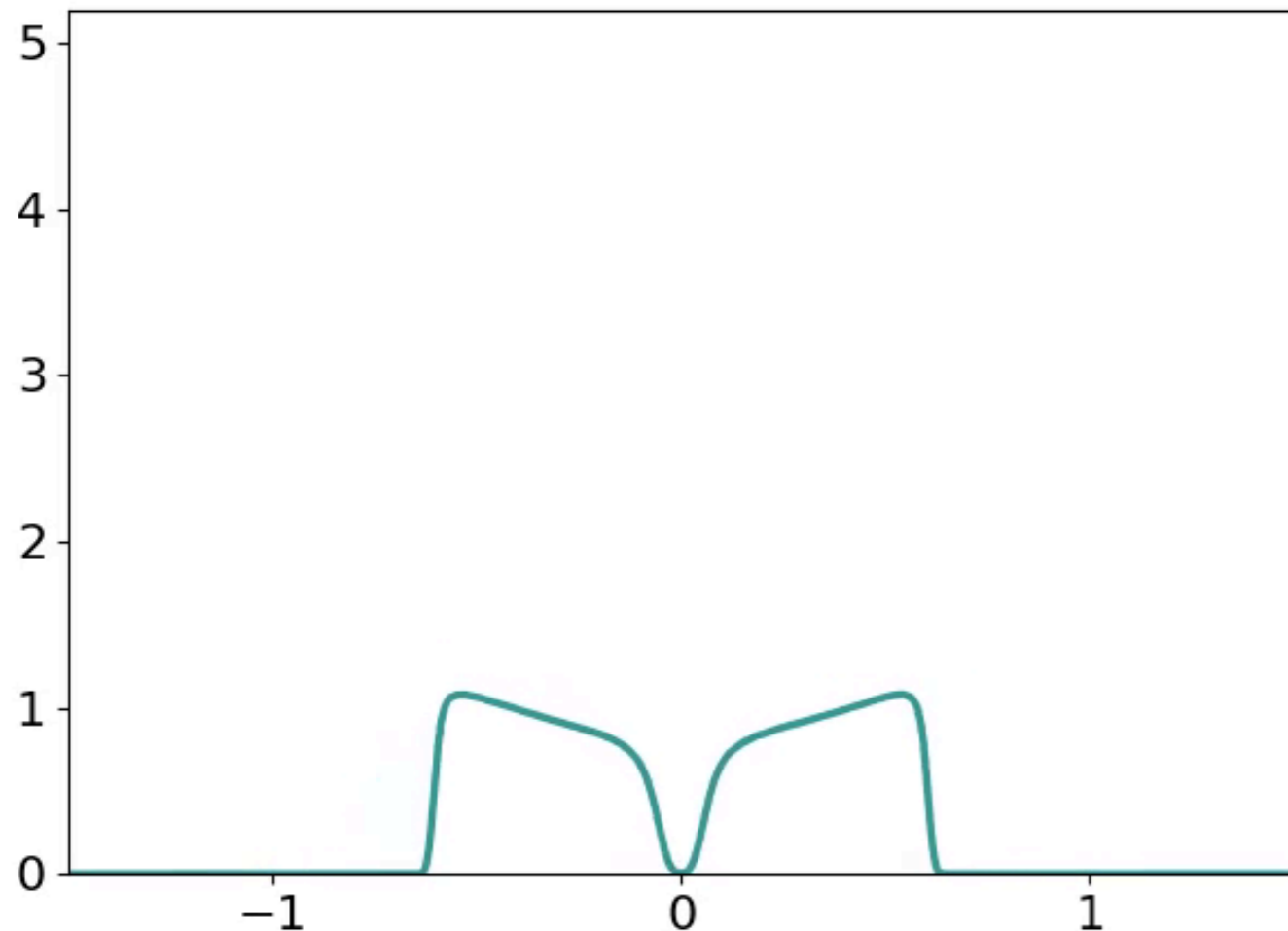


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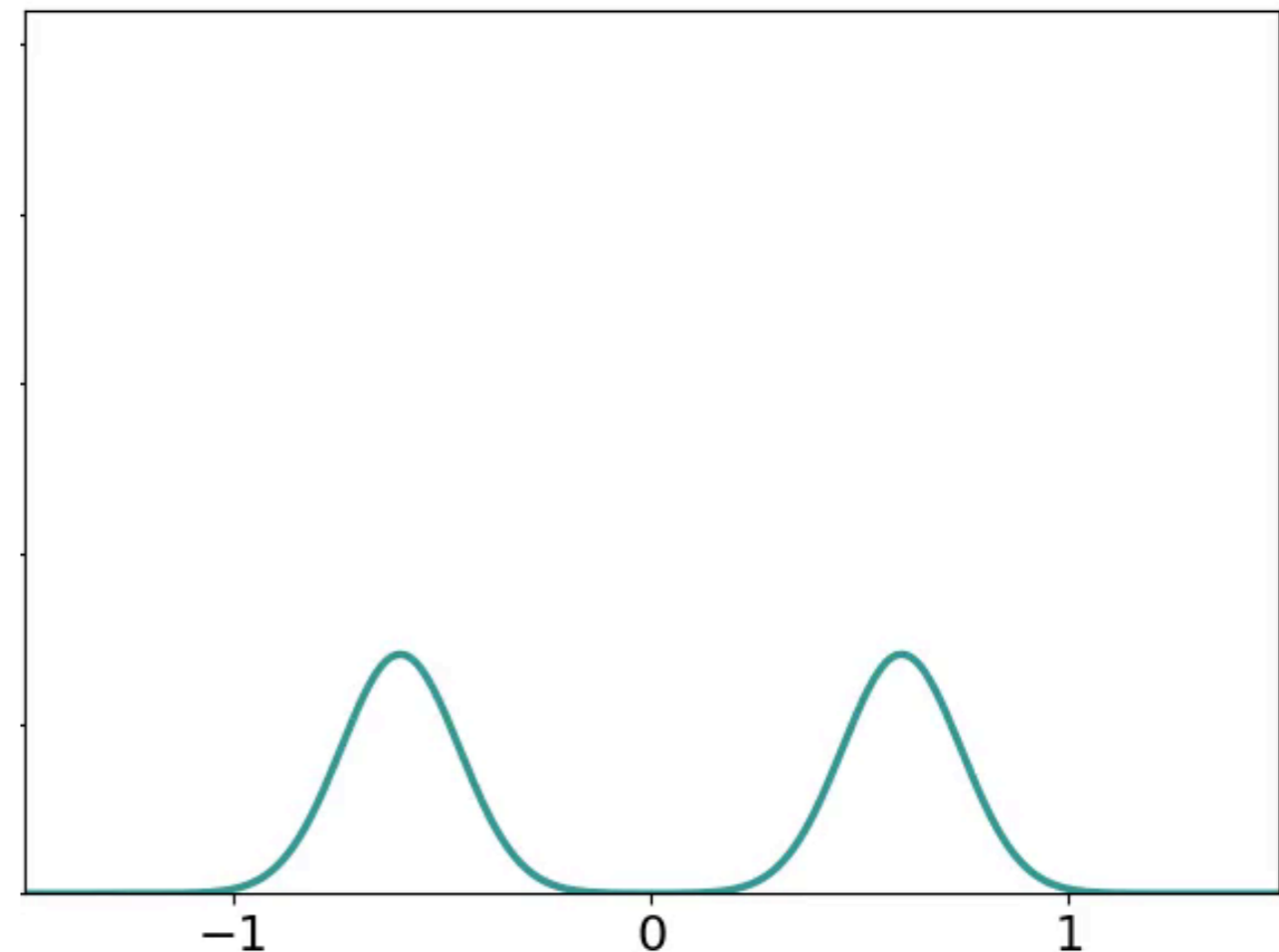
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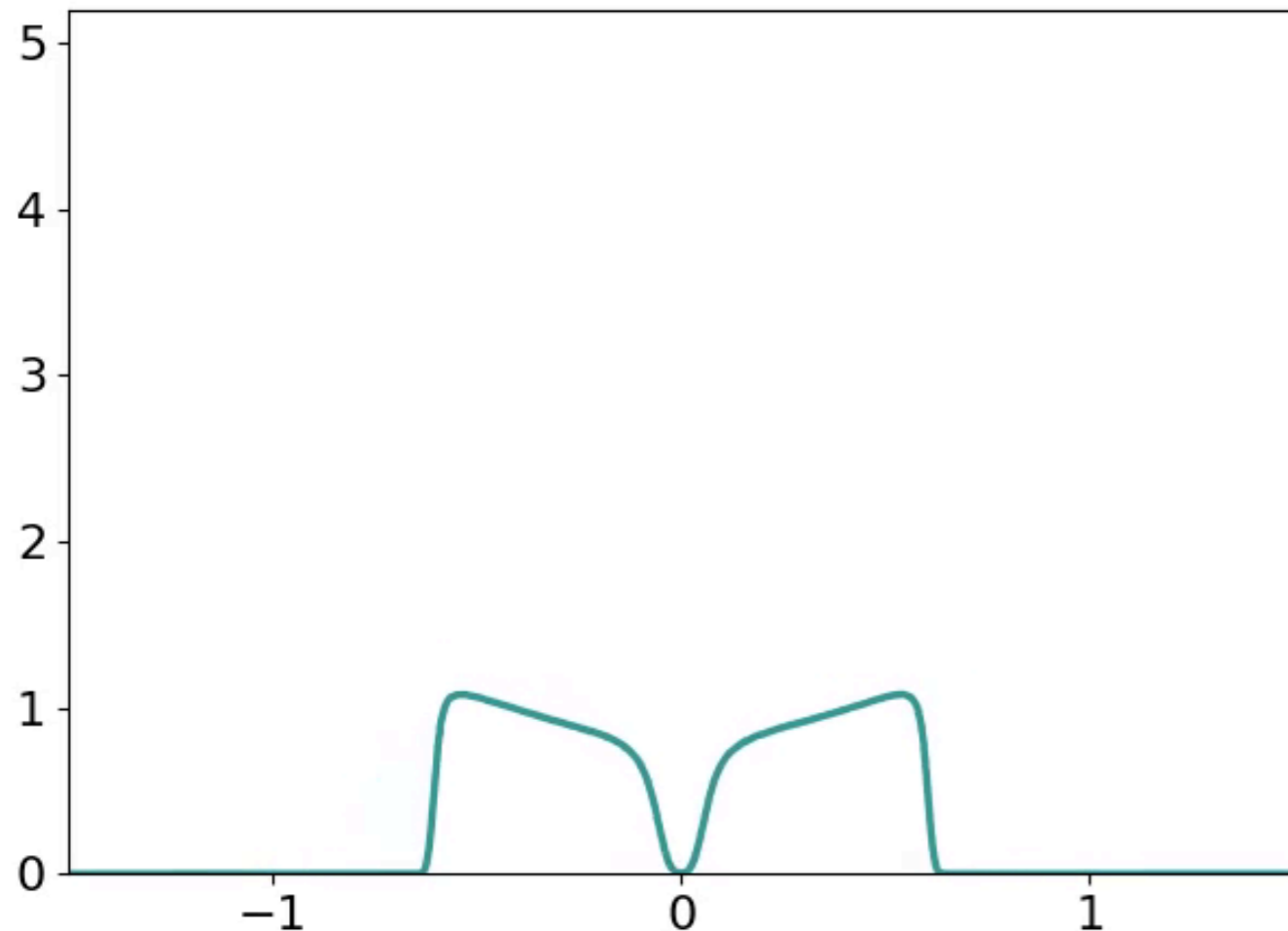


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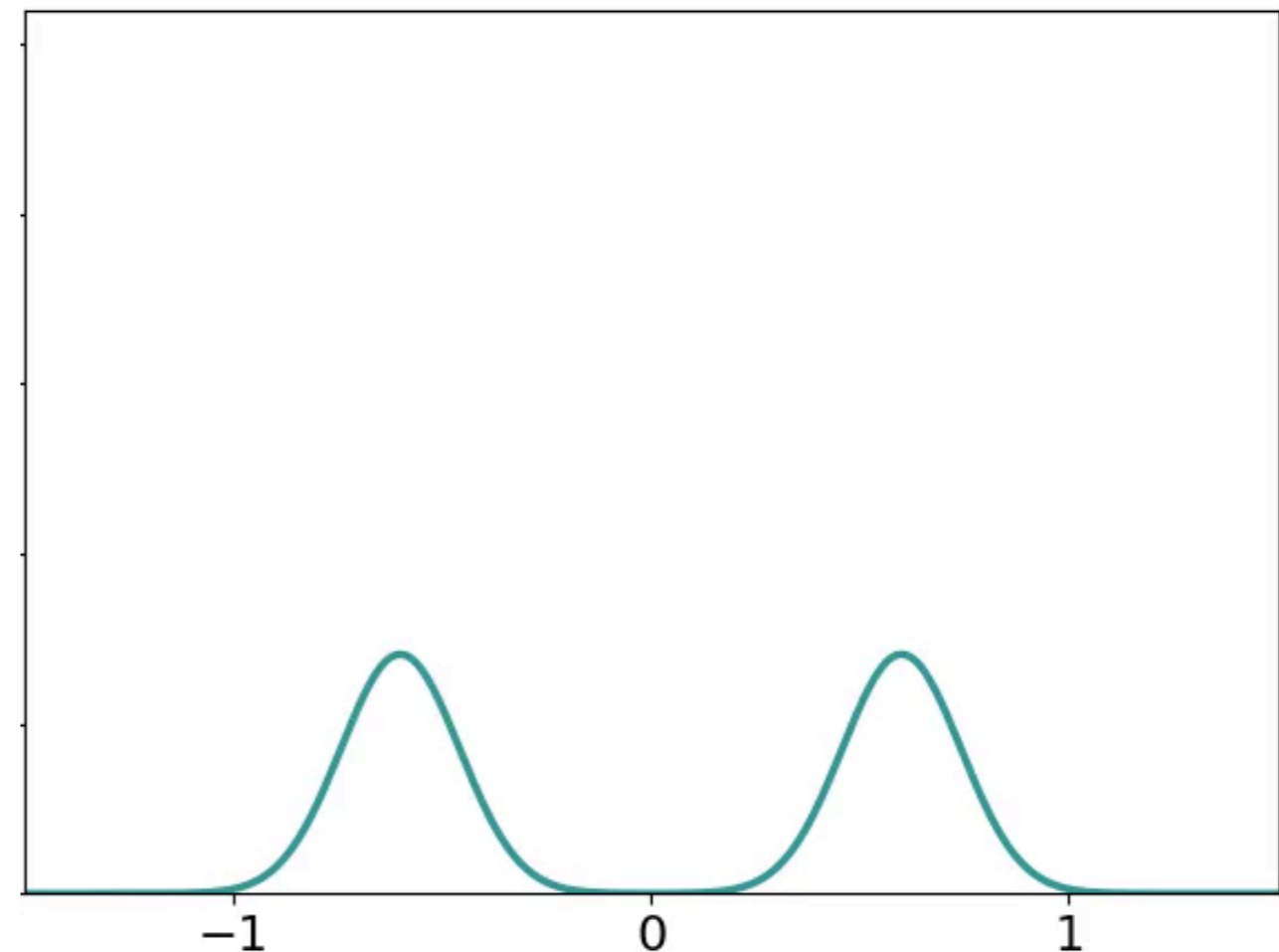
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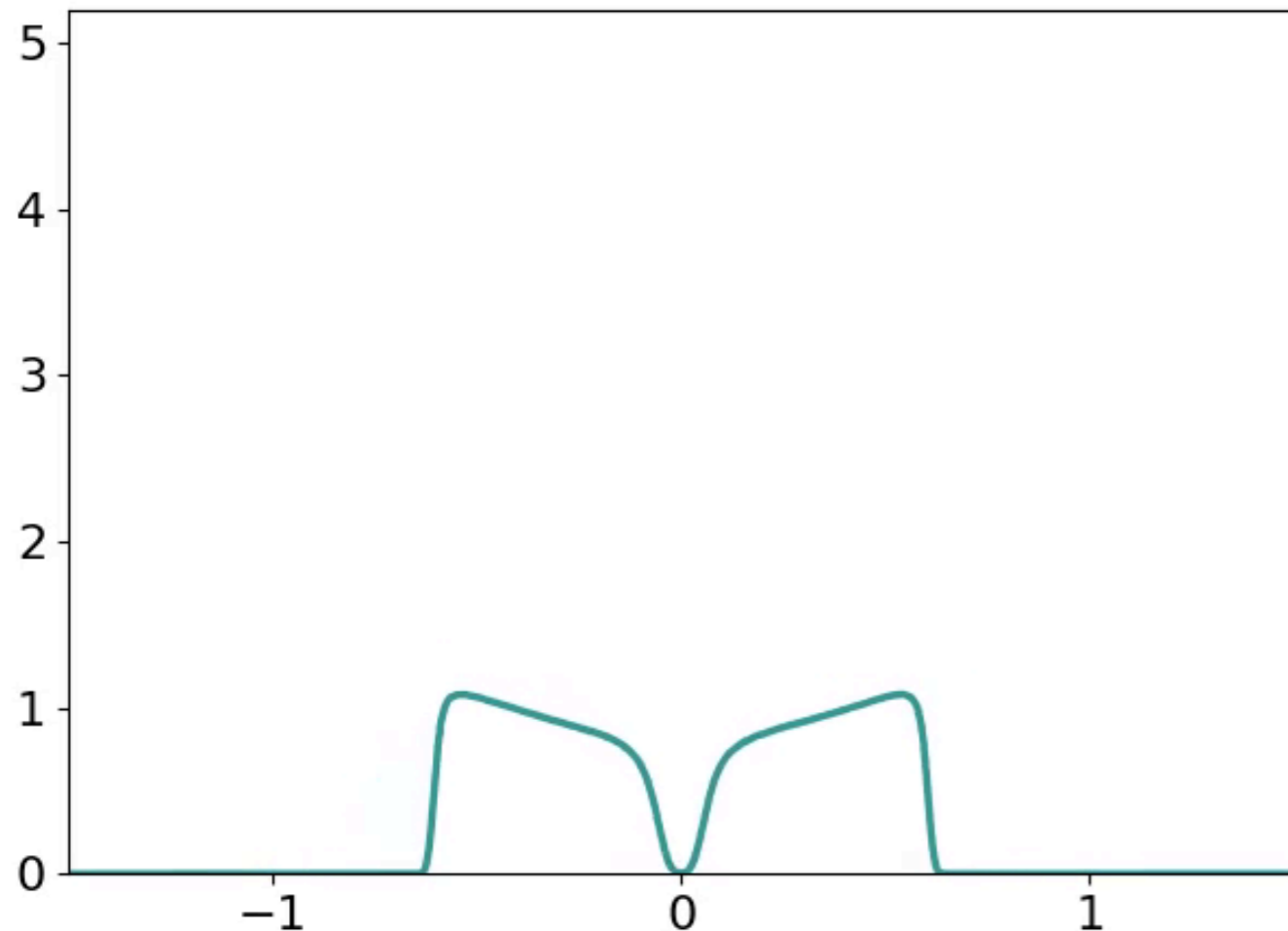


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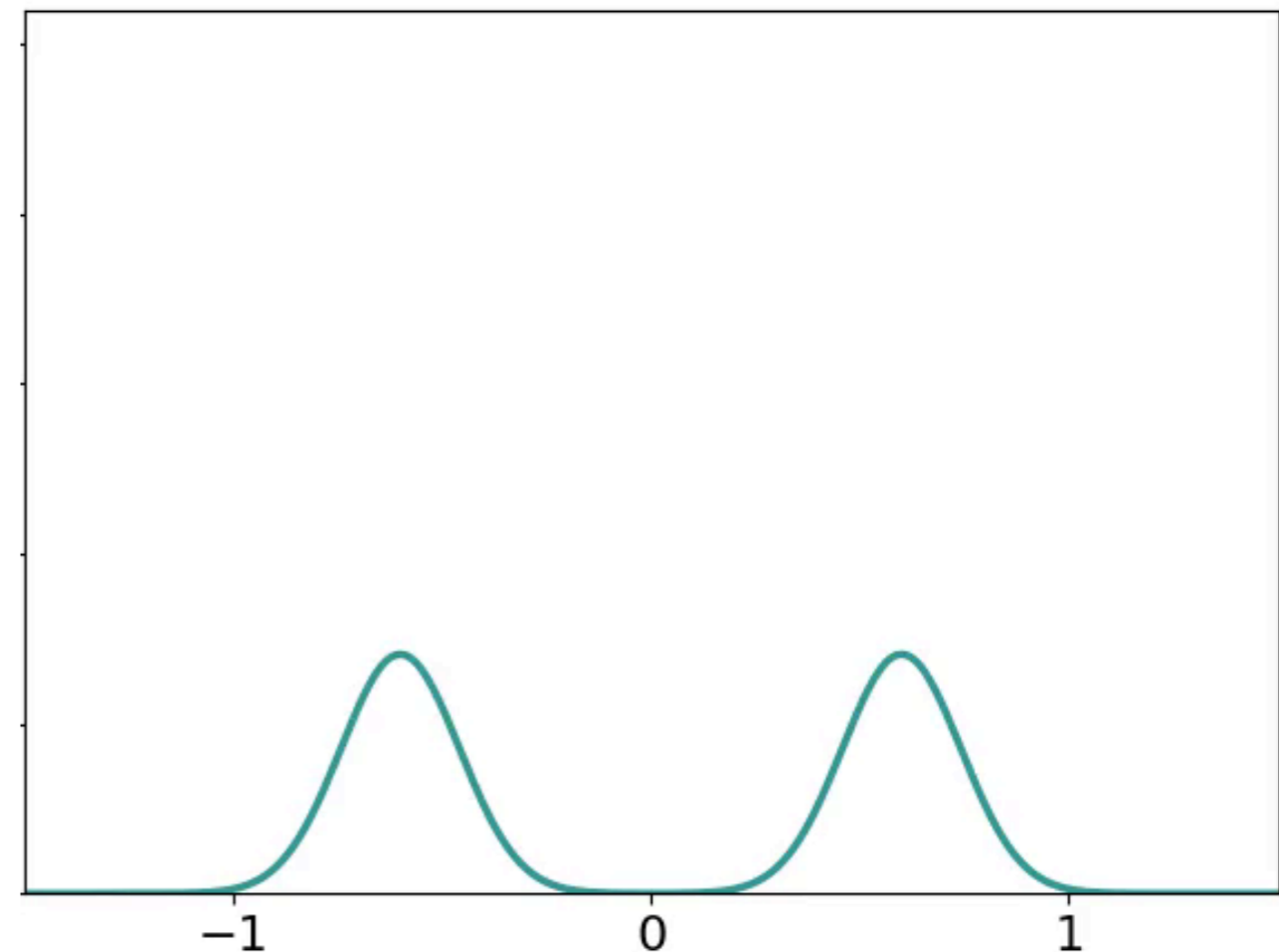
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numerical simulation of W_2 grad flow

JKO scheme

- Pros: reduces simulating grad flow to solving a sequence of optimization problems involving W_2 distance; leverages state of the art W_2 solvers.
- Cons: current methods lose **convexity/stability** properties of gradient flow

Finite volume methods, finite element methods...

- Pros: adapts numerical approaches inspired by classical fluid mechanics to gradient flow setting
- Cons: current methods lose **convexity/stability** properties of gradient flow

Without **stability**, we can't prove general results on convergence.

Particle methods

particle methods

Goal: Approximate a solution to $\frac{d}{dt}\rho(x, t) + \nabla \cdot (v(x, t)\rho(x, t)) = 0$

Assume: $v(x, t)$ comes from a Wasserstein gradient flow and is “nice”

A general recipe for a particle methods:

(1) approximate $\rho_0(x)$ as a sum of Dirac masses on a grid of spacing h

$$\rho_0 \approx \sum_{i=1}^N \delta_{x_i} m_i$$

(2) evolve the locations of the Dirac masses by

$$\frac{d}{dt}x_i(t) = v(x_i(t), t) \quad \forall i$$

(3) $\rho_N(x, t) = \sum_{i=1}^N \delta_{x_i(t)} m_i$ is a gradient flow of the original energy;

it inherits all convexity/stability properties, hence $\rho_N(x, t) \rightarrow \rho(x, t)$

particle methods

Goal: Approximate a solution to

$$\frac{d}{dt}\rho(x, t) + \nabla \cdot (v(x, t)\rho(x, t)) = 0$$

Benefits of particle methods:

- (1) positivity preserving
- (2) inherently adaptive
- (3) energy decreasing
- (4) preserves **convexity/stability** properties of gradient flow at discrete level

but what about when $v(x, t)$ is not “nice”?

$v(x,t)$ is often not nice

aggregation, drift, and degenerate diffusion:

$$\frac{d}{dt}\rho = \nabla \cdot ((\nabla K * \rho)\rho) + \nabla \cdot (\nabla V \rho) + \Delta \rho^m$$

$$v = \nabla K * \rho + \nabla V + m\rho^{m-2}\nabla \rho$$

- **Diffusion** term is worst: particles do not remain particles
- But even the **interaction** term can slow down convergence if it has a strong singularity at the origin...



$K, V : \mathbb{R}^d \rightarrow \mathbb{R}$, and $m \geq 1$

$v(x,t)$ is often not nice

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“Blob Method”: regularize the velocity field to make it nice!



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a blob method for aggregation

Goal: Approximate a solution to $\frac{d}{dt}\rho = \nabla \cdot ((\nabla K * \rho)\rho)$ $v = \nabla K * \rho$

A regularized particle method:

(0) regularize the interaction kernel via convolution with a mollifier

$$K_\epsilon(x) = K * \varphi_\epsilon(x), \quad \varphi_\epsilon(x) = \varphi(x/\epsilon)/\epsilon^d$$

(1) approximate $\rho_0(x)$ as a sum of Dirac masses on a grid of spacing h

$$\rho_0 \approx \sum_{i=1}^N \delta_{x_i} m_i$$

(2) evolve the locations of the Dirac masses by

$$\frac{d}{dt}x_i(t) = - \sum_{j=1}^N \nabla K_\epsilon(x_i(t) - x_j(t)) m_j$$

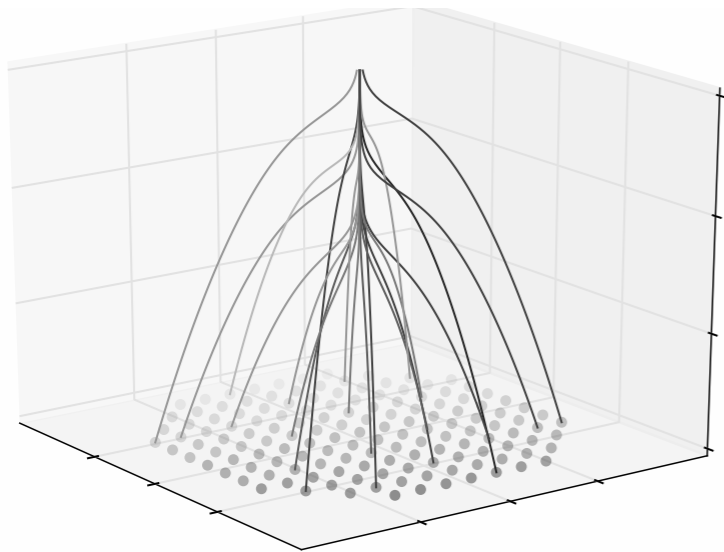
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$$E_\epsilon(\rho) = \int (K_\epsilon * \rho)\rho$$

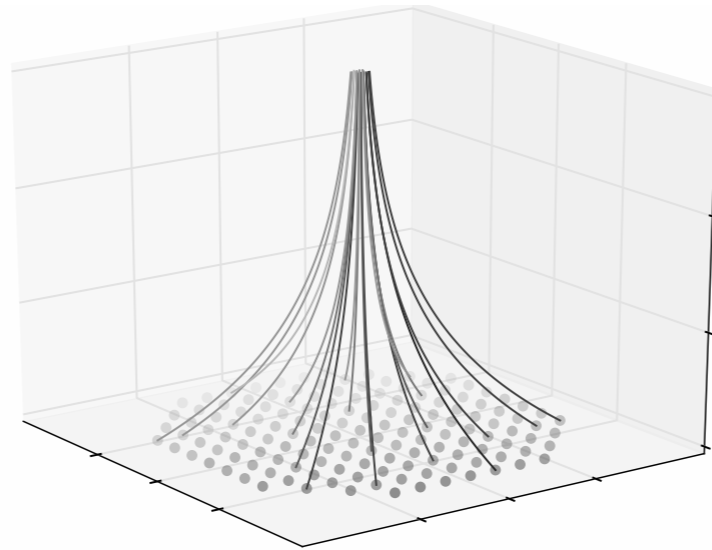
a blob method for aggregation

Theorem [C., Bertozzi 2014]: If $\varepsilon = h^q$, $0 < q < 1$, the blob method converges as $h \rightarrow 0$.

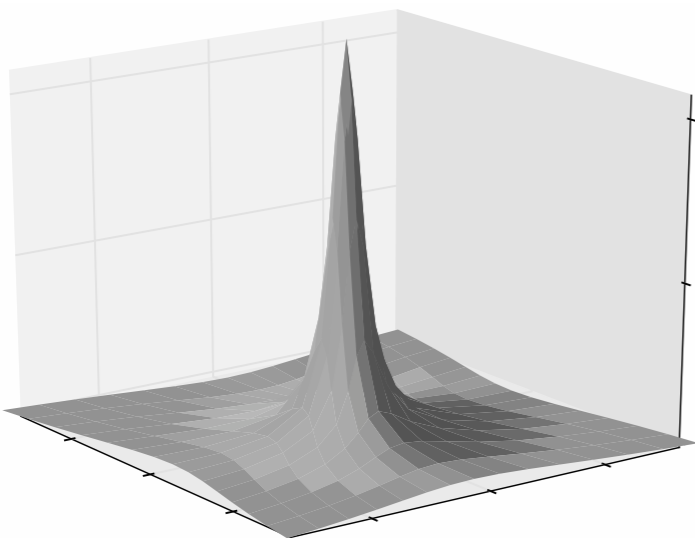
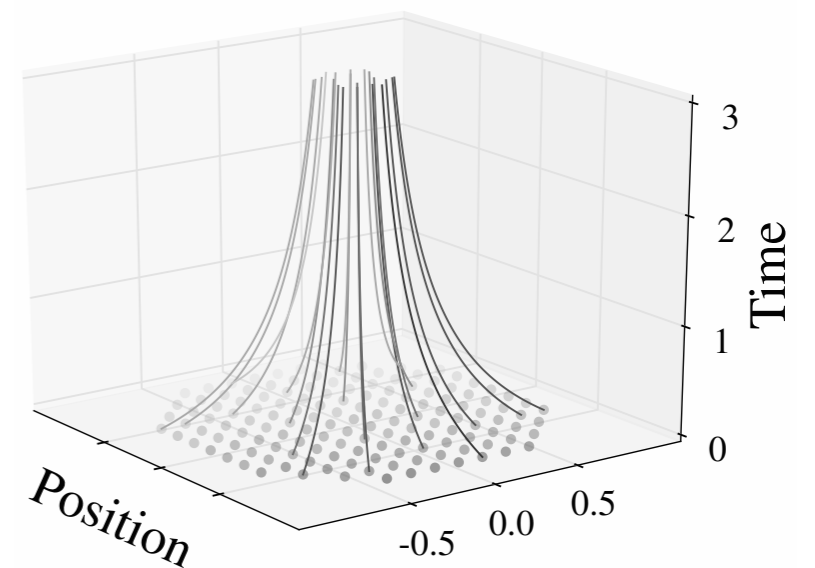
$$K(x) = \log |x| / 2\pi$$



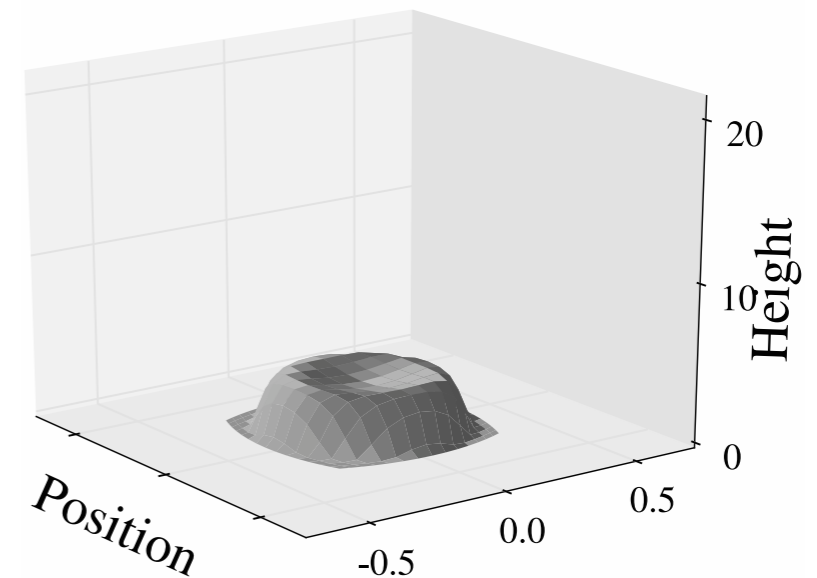
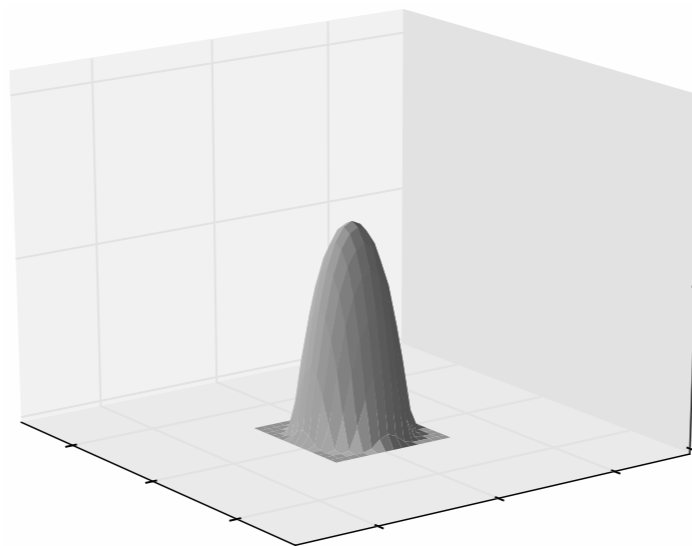
$$K(x) = |x|^2 / 2$$



$$K(x) = |x|^3 / 3$$



$$h = 0.04, q = 0.9, m = 4$$



aggregation + ?

aggregation, drift, and diffusion:

$$\frac{d}{dt}\rho = \nabla \cdot ((\nabla K * \rho)\rho) + \nabla \cdot (\nabla V \rho) + \Delta \rho^m \quad K, V : \mathbb{R}^d \rightarrow \mathbb{R}, \text{ and } m \geq 1$$

- Adding a **drift term** is straightforward: just do a particle method with
$$v = \nabla K_\epsilon * \rho + \nabla V$$
- How can we add **diffusion**?
- Previous work: **stochastic** [Liu, Yang 2017], [Huang, Liu 2015], **deterministic** [Carrillo, Huang, Patacchini, Wolansky 2016]
- Our idea: **regularize by convolution with a mollifier.**

a blob method for degenerate diffusion

diffusion equation:

$$\frac{d}{dt}\rho = \Delta\rho^m \quad m \geq 1$$

Solutions of diffusion equation are gradient flows of $E(\rho) = \frac{1}{m-1} \int \rho^m$

Let's consider gradient flows of $E_\epsilon(\rho) = \frac{1}{m-1} \int (\rho * \varphi_\epsilon)^{m-1} \rho$

- Previous work (m=2): [Lions, Mas-Gallic 2000], [P.E. Jabin, in progress]
- For $\epsilon > 0$, particles remain particles, so can do a particle method for

$$v = \nabla\varphi_\epsilon * ((\varphi_\epsilon * \rho)^{m-2} \rho) + (\varphi_\epsilon * \rho)^{m-2} (\nabla\varphi_\epsilon * \rho)$$

\implies a blob method for diffusion.

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Theorem [Carrillo, C., Patacchini 2017]: Consider

$$E_\varepsilon(\rho) = \int (K * \rho)\rho + \int V\rho + \frac{1}{m-1} \int (\rho * \varphi_\varepsilon)^{m-1}\rho$$

As $\varepsilon \rightarrow 0$,

- For all $m \geq 1$, E_ε Γ -converge to E .
- For $m = 2$ and initial data with bounded entropy, gradient flows of E_ε converge to gradient flows of E .
- For $m \geq 2$ and particle initial data with $\varepsilon = h^q$, $0 < q < 1$, if a priori estimates hold, gradient flows of E_ε converge to gradient flows of E .

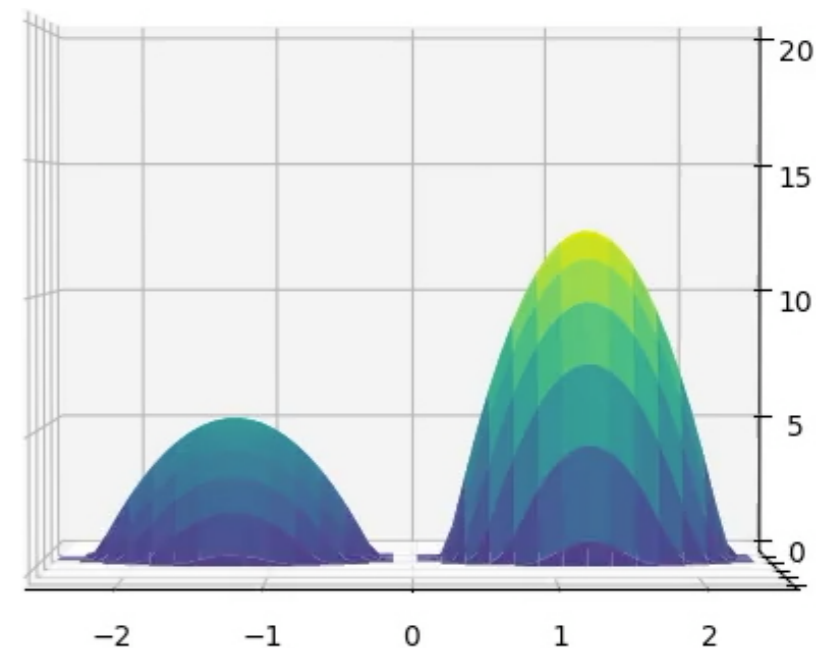
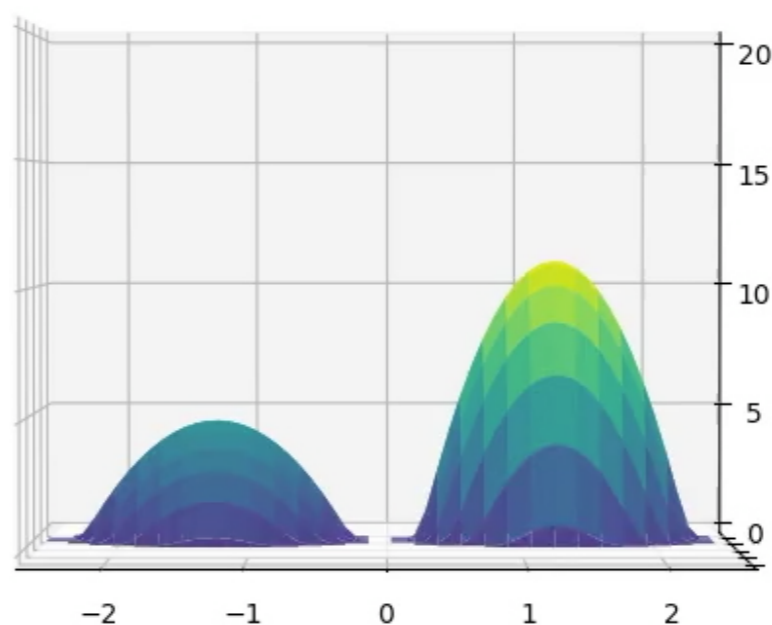
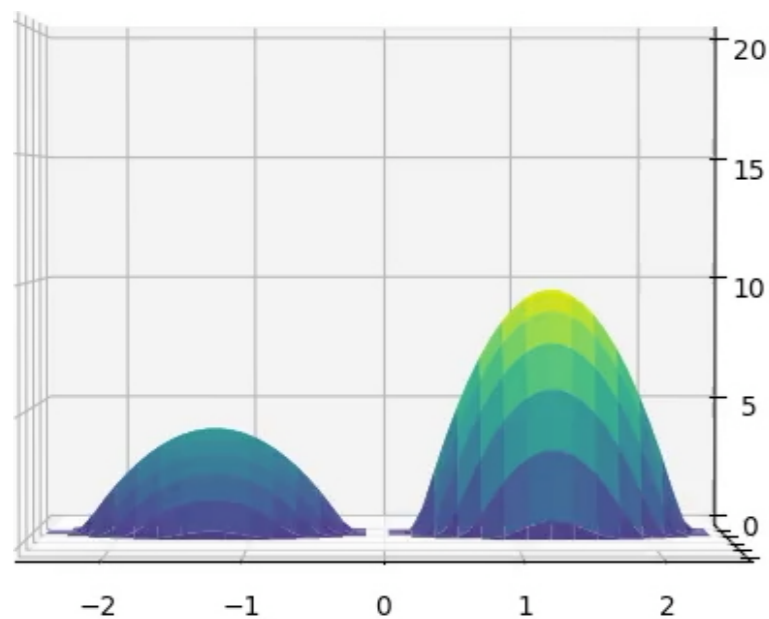
numerics: Keller-Segel (d=2)

subcritical mass

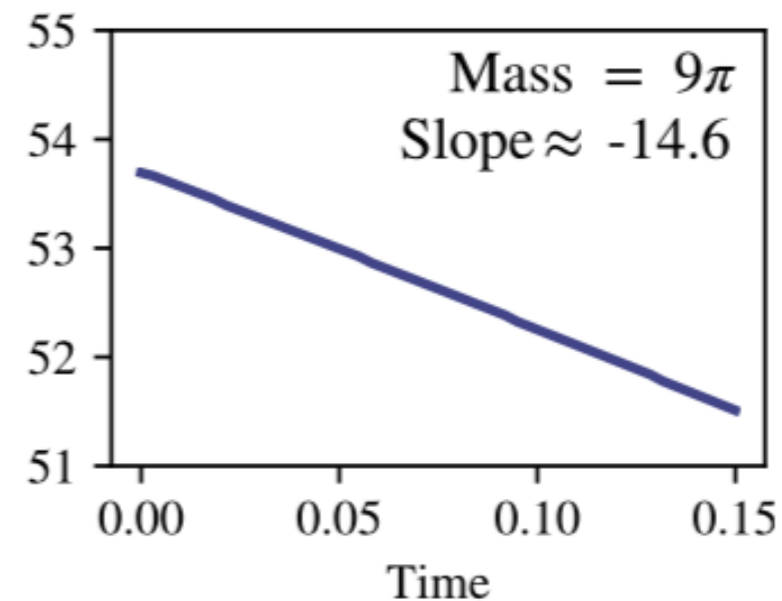
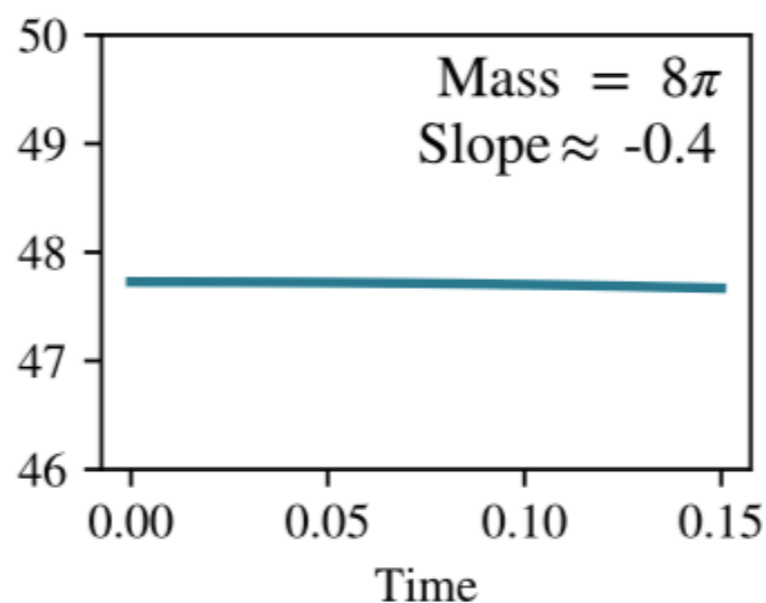
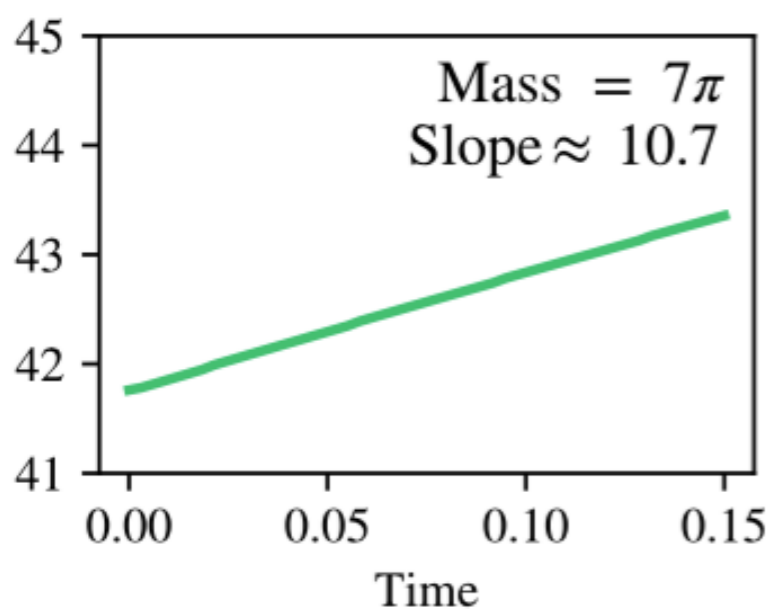
critical mass

supercritical mass

Evolution of Density



Evolution of Second Moment



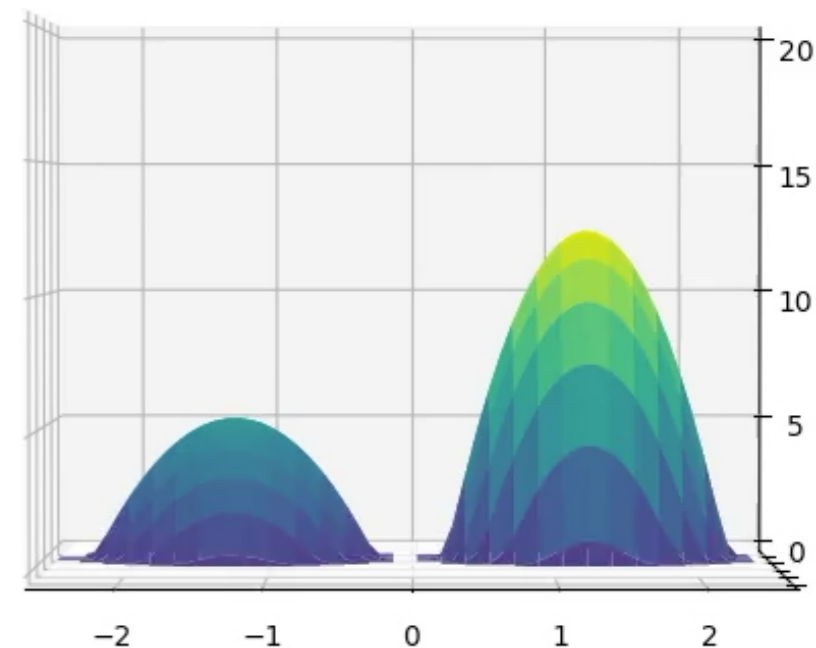
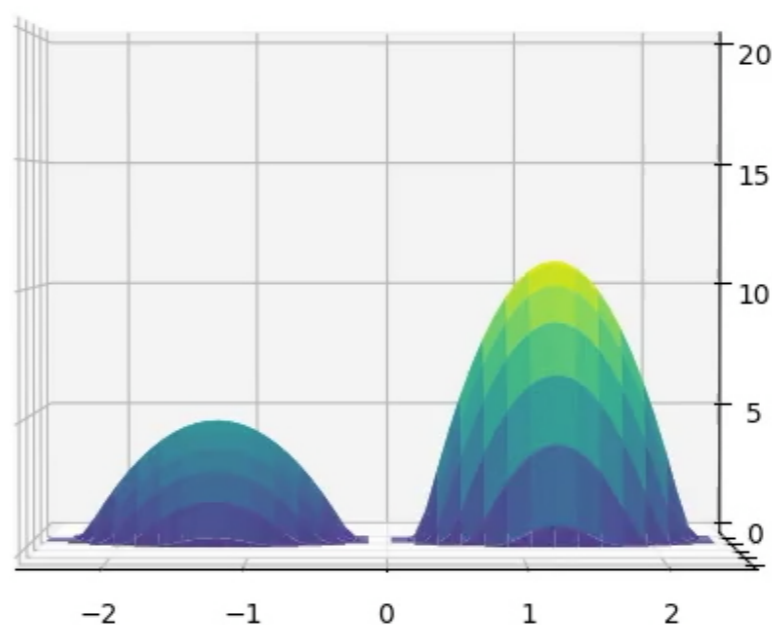
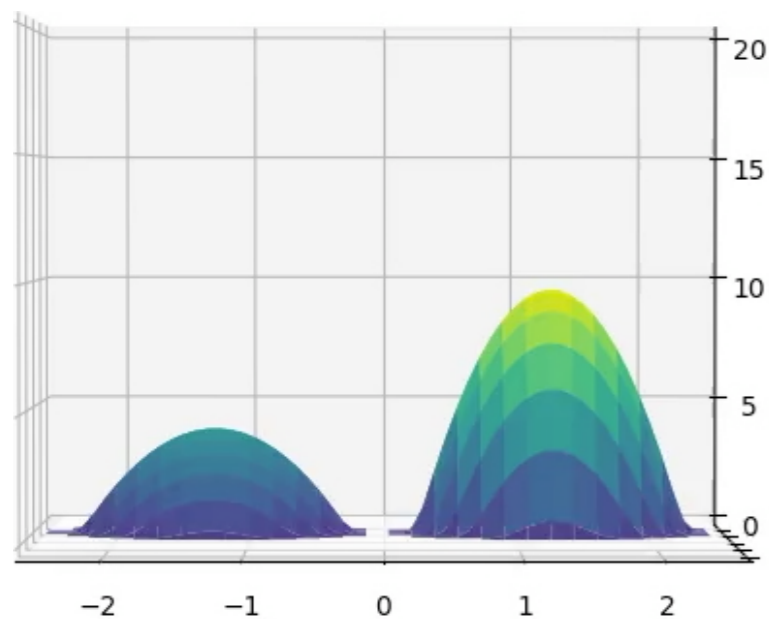
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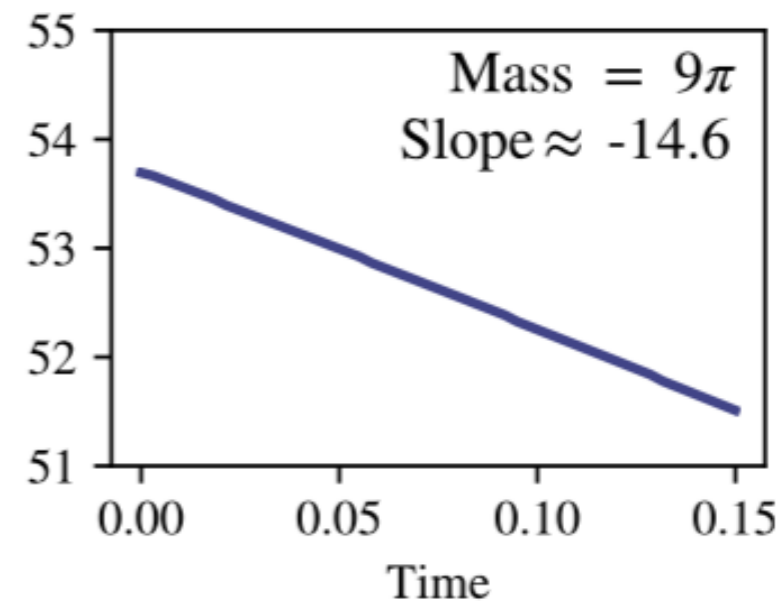
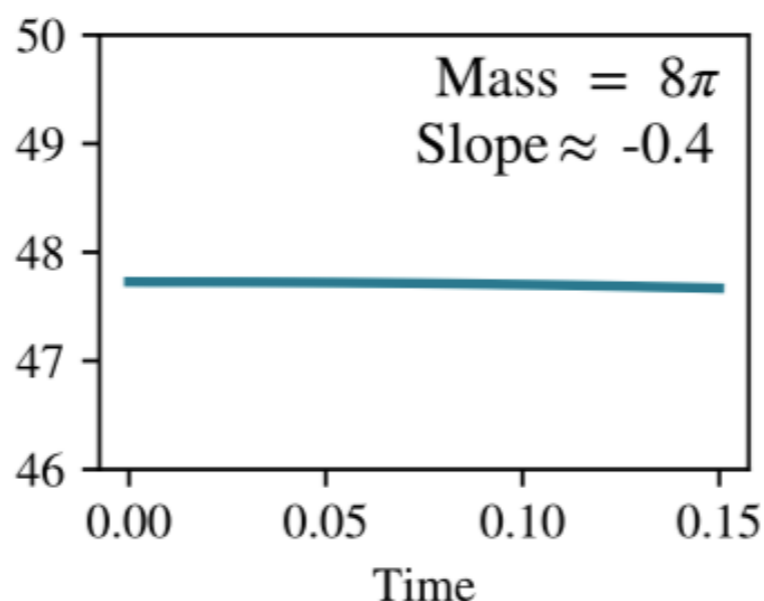
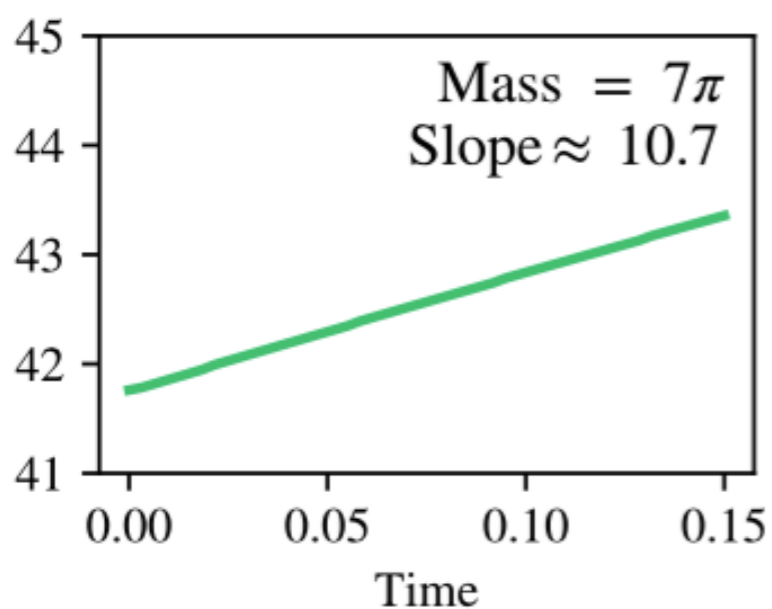
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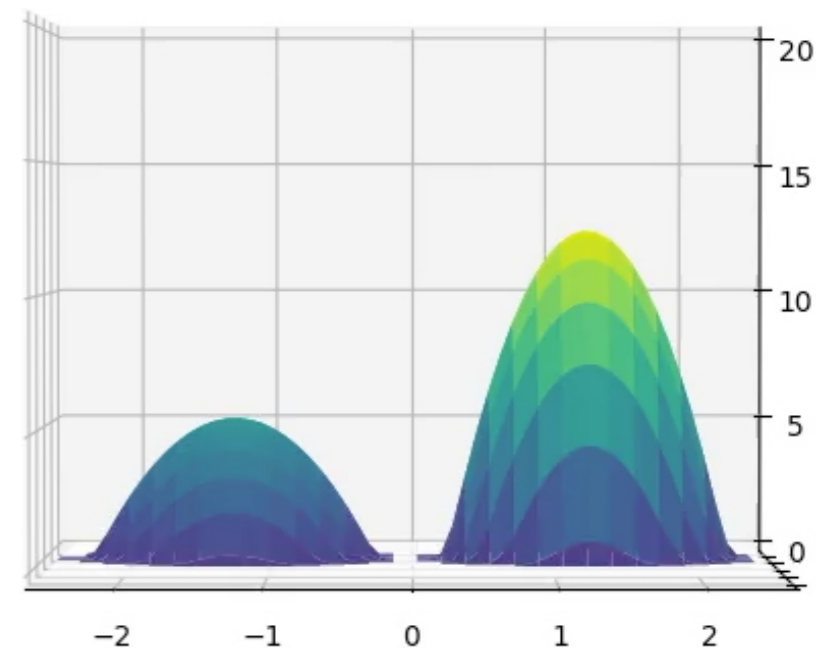
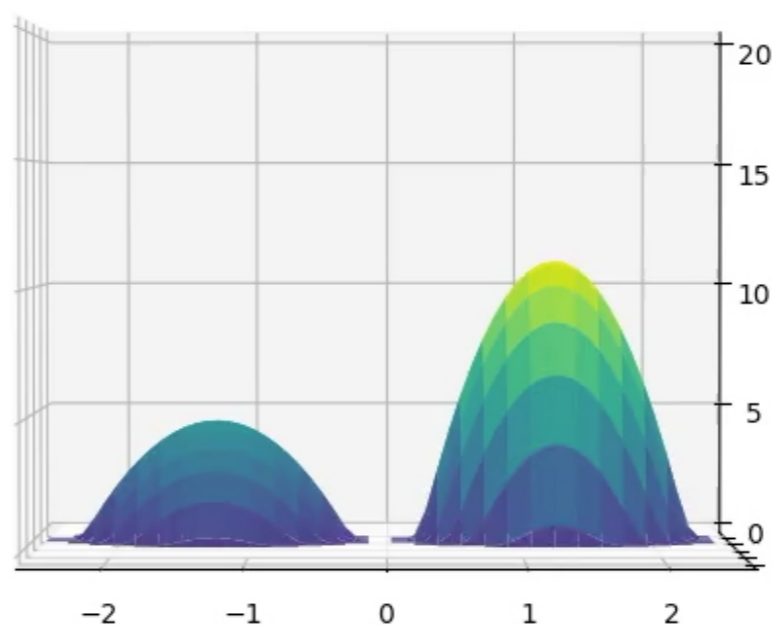
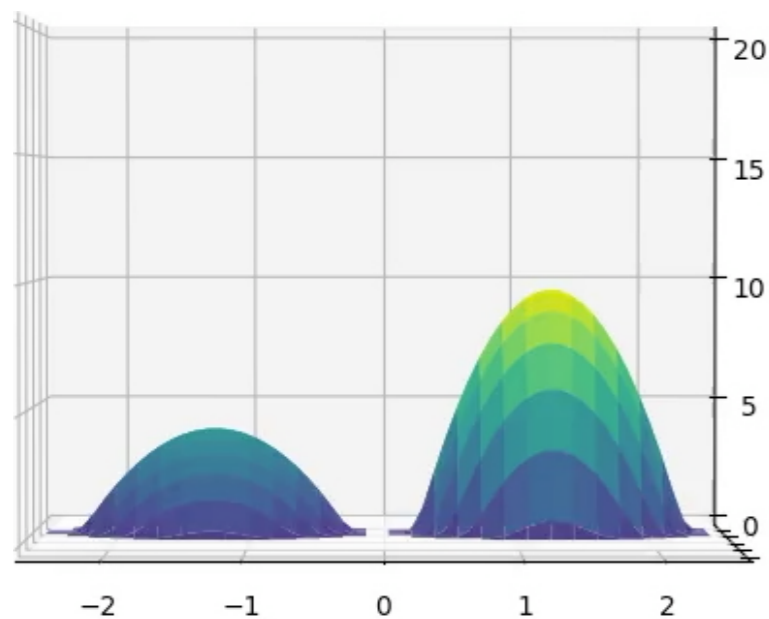
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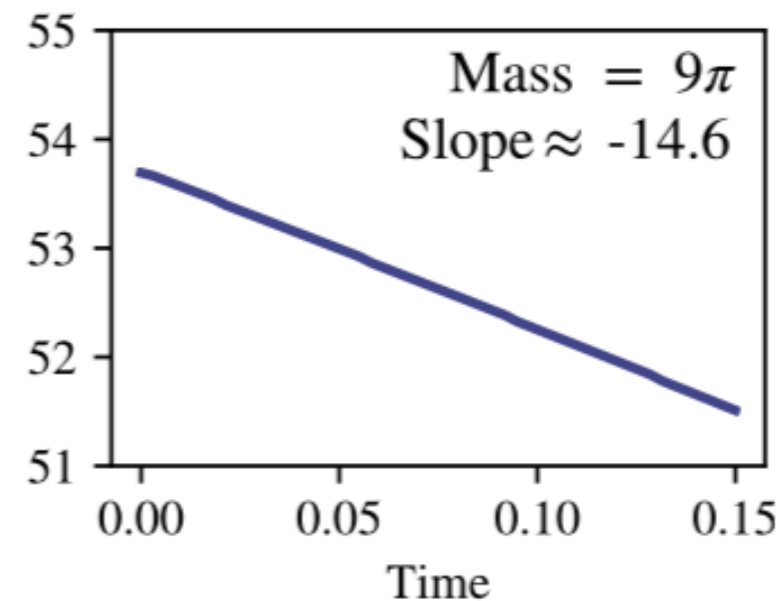
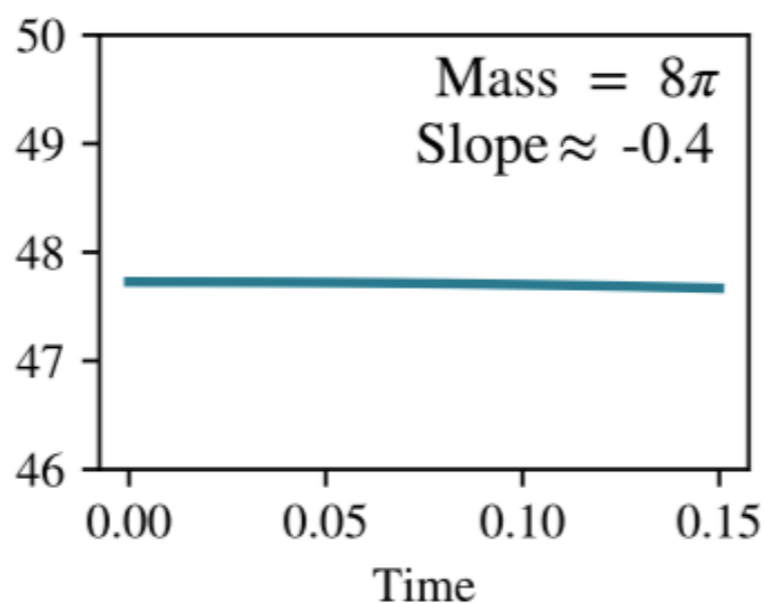
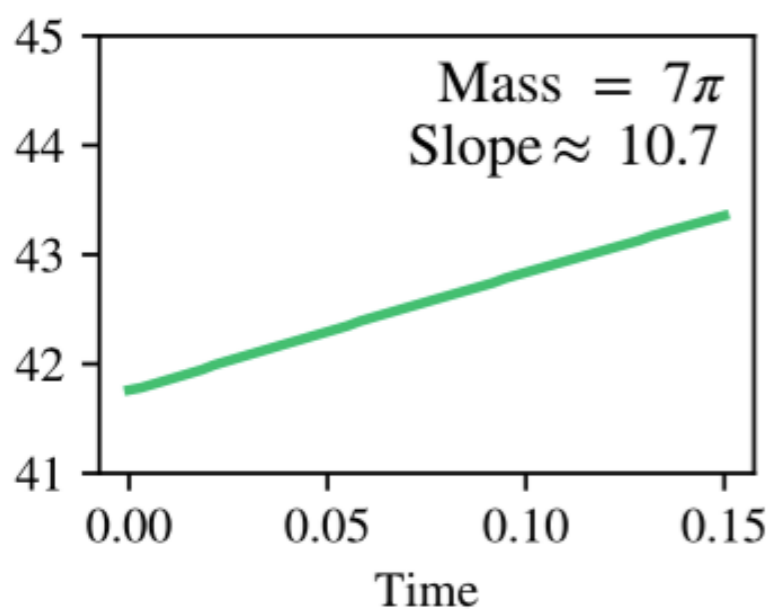
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Future work

- Convergence for $1 \leq m < 2$?
- Quantitative estimates for $m \geq 2$?
- Utility in related fluids and kinetic equations?

Thank you!